

SECTION 26 29 23
VARIABLE FREQUENCY DRIVES

PART 1 - GENERAL

1.1 SECTION INCLUDES

- A. Variable frequency drives

1.2 REFERENCES

- A. ANSI/UL Standard 508
- B. ANSI/NEMA ICS 6 - Enclosures for Industrial Controls and Systems
- C. IEEE Standard 519-1992 - Guide for Harmonic Control and Reactive Compensation of Static Power Converters
- D. FCC Rules and Regulations, Part 15, Subpart J - Radio Frequency Interference

1.3 SUBMITTALS

- A. Submit shop drawings and product data under provisions of Section 26 05 00.
- B. Shop Drawings: Include front and side views of enclosures with overall dimensions and weights shown; conduit entrance locations and requirements; and nameplate legends.
- C. Product Data: Provide catalog sheets showing voltage, controller size, ratings and size of switching and overcurrent protective devices, short circuit ratings, dimensions, and enclosure details.
- D. Manufacturer's Installation Instructions: Indicate application conditions and limitations of use stipulated by Product testing agency specified under Regulatory Requirements. Include instructions for storage, handling, protection, examination, preparation, installation, and starting of Product.
- E. Provide harmonic distortion analysis of total service to prove variable frequency drives proposed do not exceed the latest version of IEEE 519 voltage and current distortion limits as shown in Table 10.2 and 10.3 at the point of common coupling (PCC). The PCC shall be defined as the consumer-utility interface or primary side of the main distribution transformer.

1.4 OPERATION AND MAINTENANCE DATA

- A. Submit operation and maintenance data under provisions of Section 26 05 00.
- B. Maintenance Data: Include spare parts data listing, source and current prices of replacement parts and supplies, and recommended maintenance procedures and intervals.

- C. Operation Data: Include instructions for starting and operating controllers, and describe operating limits that may result in hazardous or unsafe conditions.
- D. Shop Drawings: For each VFD.
 - 1. Include dimensioned plans, elevations, sections, and details, including required clearances and service space around equipment. Show tabulations of installed devices, equipment features, and ratings. Include the following:
 - a. Each installed unit's type and details.
 - b. Nameplate legends.
 - c. Short-circuit current rating of integrated unit.
 - 2. Wiring Diagrams: Power, signal, and control wiring for VFDs. Provide schematic wiring diagram for each type of VFD.

1.5 DELIVERY, STORAGE, AND HANDLING

- A. Deliver, store, protect and handle products to site under provisions of Section 26 05 00.
- B. Accept controllers on site in original packing. Inspect for damage.
- C. Store in a clean, dry space. Maintain factory wrapping or provide an additional heavy canvas or heavy plastic cover to protect units from dirt, water, construction debris, and traffic.
- D. Handle in accordance with manufacturer's written instructions. Lift only with lugs provided for the purpose. Handle carefully to avoid damage.

1.6 EXTRA MATERIAL

- A. Furnish under provisions of Section 26 05 00.
- B. Provide two of each air filter.
- C. Provide three of each fuse size and type.

PART 2 - PRODUCTS

2.1 ACCEPTABLE MANUFACTURERS: YASHAWA, ABB, SQUARE D.

2.2 DESCRIPTION

- A. Converts 60 Hertz input power at voltage specified to a variable AC frequency and voltage for controlling the speed of AC squirrel cage motors. The controller shall be suitable for use with standard NEMA B squirrel cage 1.15 service factor induction

motors without requiring any modifications to the motor or the drive.

- B. Controller shall have sufficient capacity to provide speed control of the motors shown or noted throughout the specified environmental operating conditions.
- C. Controller shall have the functional components listed below:
 - 1. Door interlocked input circuit breaker/fused switch.
 - 2. Input rectifier section to supply fixed DC bus voltage.
 - 3. Smoothing reactor for DC bus.
 - 4. DC bus capacitors.
 - 5. Control transformer.
 - 6. Separate terminal blocks for power and control wiring.
 - 7. Terminal block for operator controls.
 - 8. Sine weighted PWM generating inverter section.

2.3 RATINGS

- A. Rated Input Voltage: Refer to Variable Frequency Drive Schedule.
- B. Motor Nameplate (Drive Output) Voltage: Refer to Variable Frequency Drive Schedule.
- C. Displacement Power Factor: Between 1.0 and 0.95, lagging, over entire range of operating speed and load.
- D. Operating Ambient: 0°C to 40°C.
- E. Minimum Relative Humidity Range: 5% to 90% (non-condensing).
- F. Minimum Elevation without Derating: 3300 feet.
- G. Minimum Efficiency at Full Load: 96 percent.
- H. Overload Capability: 1.1 times the base load current for 60 seconds; 2.0 times the base load current for 3 seconds.
- I. Starting Torque: 100 percent of rated torque or as indicated.
- J. Speed Regulation: Plus or minus 1 percent with no motor derating.

2.4 DESIGN

- A. Pulse Width Modulated (PWM) Variable Frequency Drives:
 - 1. Converter shall be of a diode bridge design with a sine-weighted PWM inverter section.
 - 2. Main semi-conductors in the inverter section of controller shall be IGBT transistors capable of a carrier switching frequency of up to 8 kHz. If derating of the inverter is necessary to run at 8kHz, then the unit's derated currents must equal or exceed the motor full load currents listed in NEC Table 430-150.

3. All controllers supplied with semi-conductors capable of switching at less than 8,000 Hertz shall be supplied with a motor acoustic noise reduction filter.
 4. Pulse width modulated (PWM) drives shall be supplied with drive input line reactors with a minimum impedance of 3%. Reactors shall be installed to filter entire drive input circuit.
 5. Drives that are located beyond the manufacturer's recommended maximum distance from the motor shall be provided with dV/dt (long lead) filters.
- B. All drives shall have built-in diagnostic capability with status and fault indicators mounted on enclosure door. Complete operating instructions for diagnostics shall be mounted inside of the enclosure door.
 - C. Drive shall restart after power loss and under-voltage fault. The minimum number of restart attempts required shall be three, field adjustable.
 - D. The drive shall allow unlimited switching of the output without damage to the drive or motor.

2.5 PRODUCT FEATURES

- A. Display: Provide integral digital display to indicate all protection faults and drive status (including overcurrent, overvoltage, undervoltage, ground fault, overtemperature, phase loss, input power ON, output voltage, output frequency, and output current.
- B. Protection:
 1. Input transient protection by means of surge suppressors.
 2. Snubber networks to protect against malfunctions due to system transients,
 3. Under- and overvoltage trips; inverter overtemperature, overload, and overcurrent trips.
 4. Motor thermal overload relay(s) adjustable and capable of NEMA 250 and sized per motor nameplate data.
 5. Notch filter to prevent operation of the controller-motor-load combination at a natural frequency of the combination.
 6. Instantaneous line-to-line and line-to-ground overcurrent trips on input and output.
 7. Loss-of-phase protection.
 8. Reverse-phase protection.
 9. Short-circuit protection (fuses or circuit breaker).

10. Motor overtemperature fault.
- C. Acceleration Rate Adjustment: 0.5 - 30 seconds.
 - D. Deceleration Rate Adjustment: 1 - 30 seconds.
 - E. Minimum Adjustment Range for the Lower Output Frequency shall be: 0 to 40 Hertz.
 - F. Minimum Adjustment Range for the Upper Output Frequency Range shall be: 40 to 90 Hertz.
 - G. Minimum Volts/Hertz Range: 3.7 to 8.6 volts/Hertz.
 - H. Provide MANUAL-OFF-AUTOMATIC selector switch and manual analog speed control mounted on the front of the enclosure.
 - I. Safety Interlocks: Provide terminals for remote contact to inhibit starting under both manual and automatic mode.
 - J. Control Interlocks: Provide terminals for remote contact to allow starting in automatic mode.
 - K. Provide adjustable skip frequencies on the drive output (minimum of three ranges).
 - L. Automatic Reset/Restart: Attempts three restarts after controller fault or on return of power after an interruption, and before shutting down for manual reset or fault correction. Bidirectional autospeed search shall be capable of starting into rotating loads spinning in either direction and returning motor to set speed in proper direction, without damage to controller, motor, or load.
 - M. Power-Interruption Protection: After a power interruption, it prevents the motor from re-energizing until the motor has stopped.
 - N. Torque Boost: Automatically varies starting and continuous torque to at least 1.5 times the minimum torque to ensure high-starting torque and increased torque at slow speeds.
 - O. Motor Temperature Compensation at Slow Speeds: Adjustable current fall-back based on output frequency for temperature protection of self-cooled, fan-ventilated motors at slow speeds.
 - P. Status Lights: Door-mounted LED indicators shall indicate the following conditions:
 - 1. Power on.
 - 2. Run.
 - 3. Overvoltage.
 - 4. Line fault.
 - 5. Overcurrent.
 - 6. External fault.

- Q. Panel-Mounted Operator Station: Start-stop and auto-manual selector switches with manual speed control potentiometer and elapsed time meter.

- R. Indicating Devices: Meters or digital readout devices and selector switch, mounted flush in controller door and connected to indicate the following controller parameters:
 - 1. Output frequency (Hz).
 - 2. Motor speed (rpm).
 - 3. Motor status (running, stop, fault).
 - 4. Motor current (amperes).
 - 5. Motor torque (percent).
 - 6. Fault or alarming status (code).
 - 7. PID feedback signal (percent).
 - 8. DC-link voltage (VDC).
 - 9. Set-point frequency (Hz).
 - 10. Motor output voltage (V).

- S. Control Signal Interface:
 - 1. Electric Input Signal Interface: A minimum of 2 analog inputs (0 to 10 V or 0/4-20 mA) and 6 programmable digital inputs.

 - 2. Remote Signal Inputs: Capability to accept any of the following speed-setting input signals from the BMS or other control systems:
 - a. 0 to 10-V dc.
 - b. 0-20 or 4-20 mA.
 - c. Potentiometer using up/down digital inputs.
 - d. Fixed frequencies using digital inputs.
 - e. RS485.
 - f. Keypad display for local hand operation.

 - 3. Output Signal Interface:
 - a. A minimum of 1 analog output signal (0/4-20 mA), which can be programmed to any of the following:
 - 1) Output frequency (Hz).
 - 2) Output current (load).
 - 3) DC-link voltage (VDC).
 - 4) Motor torque (percent).
 - 5) Motor speed (rpm).
 - 6) Set-point frequency (Hz).

 - 4. Remote Indication Interface: A minimum of 2 dry circuit relay outputs (120-V ac, 1A) for remote indication of the following:
 - a. Motor running.
 - b. Set-point speed reached.
 - c. Fault and warning indication (overtemperature or overcurrent).
 - d. PID high- or low-speed limits reached.

- T. Communications: Provide a communications card to interface VFD with Facility Management Control System (FMCS). Coordinate interface requirements with the FMCS provided under Section 23 09 00. Interface shall allow all parameter settings of VFD to be programmed via FMCS control and displayed on FMCS operator workstation. Provide capability for VFD to retain these settings within the nonvolatile memory.
- U. Three-Contactor Manual Bypass:
1. Provide contactors, motor running overload protection, under-voltage and loss of phase protection, and short circuit protection for full voltage, non-reversing operation of the motor. Include isolation switch or third contactor to allow maintenance of inverter during bypass operation.
 2. All bypass circuitry shall be located within the same enclosure as the variable frequency drive.
 3. All fire alarm and/or smoke control interconnections (e.g., air handling unit shutdown) shall apply regardless of whether control is through VFD or bypass.
 4. Provide a Drive-Bypass Selector Switch.
 5. Provide nameplate with instructions for switching from drive to bypass and from bypass to drive. Provide instructions for isolating VFD for maintenance.
- V. Control:
1. With the "Manual-Off-Auto" switch in the "Manual" position and, if applicable, the "Drive-Bypass" in the "Drive" position, the drive shall be controlled by the manual speed potentiometer on the drive door.
 2. With the "Manual-Off-Auto" switch in the "Auto" position and, if applicable, the "Drive-Bypass" in the "Drive" position, the drive shall be controlled by the input signal from an external source.
 3. If applicable, with the "Drive-Bypass" in the "Bypass" position, regardless the position of the "Manual-Off-Auto" switch, the motor shall be connected across the lines and shall be run at full speed.
 4. With the "Manual-Off-Auto" switch in the "Off" position, if applicable, the drive run circuit shall be open and the VFD shall not operate.
 5. If applicable, signal from the fire alarm control panel shall shut down VFD and bypass.
 6. All disconnect switches between VFD and motor(s) shall include an auxiliary contact interlock wired to the VFD

fault trip input to shut down the drive upon opening of the disconnect main contacts.

2.6 ACCESSORIES

- A. Devices shall be factory installed in controller enclosure, unless otherwise indicated.
- B. All VFD supplied for fans shall have dynamic or DC injection braking capability to provide a means of rapid deceleration of the AC motor. Adjust controls to the fastest deceleration rate.
- C. Push-Button Stations, Pilot Lights, and Selector Switches: NEMA ICS 2, heavy-duty type.
- D. Stop and Lockout Push-Button Station: Momentary-break, push-button station with a factory-applied hasp arranged so padlock can be used to lock push button in depressed position with control circuit open.
- E. Control Relays: Auxiliary and adjustable time-delay relays.
- F. Standard Displays:
 - 1. Output frequency (Hz).
 - 2. Set-point frequency (Hz).
 - 3. Motor current (amperes).
 - 4. DC-link voltage (VDC).
 - 5. Motor torque (percent).
 - 6. Motor speed (rpm).
 - 7. Motor output voltage (V).
- G. Historical Logging Information and Displays:
 - 1. Real-time clock with current time and date.
 - 2. Running log of total power versus time.
 - 3. Total run time.
 - 4. Fault log, maintaining last four faults with time and date stamp for each.
- H. Fabrication:
 - 1. Enclosure: NEMA 250, Type 1.
 - 2. Finish: Manufacturer's standard enamel.

PART 3 - EXECUTION

3.1 FACTORY TESTING

- A. The VFD manufacturer shall provide certification that heat test has been completed.
- B. The Electrical Contractor shall have a factory service engineer present for the start-up, field calibration, and check-out of each VFD installed. Factory service engineer shall be required to return to the site for recalibration or set-up should unit not

function as specified during system commissioning. All costs shall be a part of This Contract. Provide tag with date and signature of factory service Engineer on inside cover of each drive.

3.2 INSTALLATION

- A. Install variable frequency drive equipment in accordance with the manufacturer's instructions.
- B. Floor mount VFD on prefabricated or field fabricated supports with controls no higher than 6'-6" and no lower than 3'-0" AFF. Mount supports on 1/2" thick vibration isolation pads set on concrete housekeeping pads.
- C. Provide engraved phenolic nameplates under the provisions of Section 26 05 53.
- D. Connections: All conduit connections to the VFD shall be by flexible conduit.
- E. Input, output, and control wiring shall each be run in separate conduits.

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