

SECTION 26 29 11
MOTOR CONTROLLERS

PART 1 - GENERAL

1.1 DESCRIPTION

- A. This section specifies the furnishing, installation, connection, and testing of motor controllers, including all low-voltage variable speed motor controllers.

1.2 RELATED WORK

- A. Section 26 05 11, REQUIREMENTS FOR ELECTRICAL INSTALLATIONS:
Requirements that apply to all sections of Division 26.
- B. Section 26 05 21, LOW-VOLTAGE ELECTRICAL POWER CONDUCTORS AND CABLES:
Low-voltage conductors.
- C. Section 26 05 26, GROUNDING AND BONDING FOR ELECTRICAL SYSTEMS:
Requirements for personnel safety and to provide a low impedance path for possible ground fault currents.
- D. Section 26 05 33, RACEWAY AND BOXES FOR ELECTRICAL SYSTEMS: Conduits.

1.3 QUALITY ASSURANCE

- A. Refer to Paragraph, QUALIFICATIONS (PRODUCTS AND SERVICES), in Section 26 05 11, REQUIREMENTS FOR ELECTRICAL INSTALLATIONS.

1.4 SUBMITTALS

- A. Submit six copies of the following in accordance with Section 26 05 11, REQUIREMENTS FOR ELECTRICAL INSTALLATIONS.
 - 1. Shop Drawings:
 - a. Submit sufficient information to demonstrate compliance with drawings and specifications.
 - b. Include electrical ratings, dimensions, weights, mounting details, materials, overcurrent protection devices, overload relays, sizes of enclosures, wiring diagrams, starting characteristics, interlocking, and accessories.
 - 2. Manuals:
 - a. Submit, simultaneously with the shop drawings, companion copies of complete maintenance and operating manuals, including technical data sheets, wiring diagrams, and information for ordering replacement parts.
 - 1) Wiring diagrams shall have their terminals identified to facilitate installation, maintenance, and operation.
 - 2) Wiring diagrams shall indicate internal wiring for each item of equipment and interconnections between the items of equipment.

- 3) Elementary schematic diagrams shall be provided for clarity of operation.
- 4) Include the catalog numbers for the correct sizes of overload relays for the motor controllers.
- b. If changes have been made to the maintenance and operating manuals originally submitted, submit updated maintenance and operating manuals two weeks prior to the final inspection.
3. Certifications: Two weeks prior to final inspection, submit the following.
 - a. Certification by the manufacturer that the motor controllers conform to the requirements of the drawings and specifications.
 - b. Certification by the Contractor that the motor controllers have been properly installed, adjusted, and tested.

1.5 APPLICABLE PUBLICATIONS

- A. Publications listed below (including amendments, addenda, revisions, supplements, and errata) form a part of this specification to the extent referenced. Publications are referenced in the text by basic designation only.
- B. Institute of Electrical and Electronic Engineers (IEEE):
 - 519-92.....Recommended Practices and Requirements for
Harmonic Control in Electrical Power Systems
 - C37.90.1-02.....Standard Surge Withstand Capability (SWC) Tests
for Relays and Relay Systems Associated with
Electric Power Apparatus
- C. International Code Council (ICC):
 - IBC-12.....International Building Code
- D. National Electrical Manufacturers Association (NEMA):
 - ICS 1-08.....Industrial Control and Systems: General
Requirements
 - ICS 1.1-09.....Safety Guidelines for the Application,
Installation and Maintenance of Solid State
Control
 - ICS 2-05.....Industrial Control and Systems Controllers,
Contactors, and Overload Relays Rated 600 Volts
 - ICS 4-05.....Industrial Control and Systems: Terminal Blocks
 - ICS 6-06.....Industrial Control and Systems: Enclosures
 - ICS 7-06.....Industrial Control and Systems: Adjustable-
Speed Drives

ICS 7.1-06.....Safety Standards for Construction and Guide for
Selection, Installation, and Operation of
Adjustable-Speed Drive Systems

MG 1 Part 31.....Inverter Fed Polyphase Motor Standards

E. National Fire Protection Association (NFPA):

70-11.....National Electrical Code (NEC)

F. Underwriters Laboratories Inc. (UL):

508A-07.....Industrial Control Panels

508C-07.....Power Conversion Equipment

UL 1449-06.....Surge Protective Devices

PART 2 - PRODUCTS

2.1 NOT USED

2.2 NOT USED

2.3 NOT USED

2.4 NOT USED

2.5 NOT USED

2.6 LOW-VOLTAGE VARIABLE SPEED MOTOR CONTROLLERS (VSMC)

A. VSMC shall be in accordance with applicable portions of 2.1 above.

B. VSMC shall be electronic, with adjustable frequency and voltage, three phase output, capable of driving standard NEMA B three-phase induction motors at full rated speed. The control technique shall be pulse width modulation (PWM), where the VSMC utilizes a full wave bridge design incorporating diode rectifier circuitry. Silicon controlled rectifiers or other control techniques are not acceptable.

C. VSMC shall be suitable for variable torque loads, and shall be capable of providing sufficient torque to allow the motor to break away from rest upon first application of power.

D. VSMC shall be capable of operating within voltage parameters of plus 10 to minus 15 percent of line voltage, and be suitably rated for the full load amps of the maximum watts (HP) within its class.

E. Minimum efficiency shall be 95 percent at 100 percent speed and 85 percent at 50 percent speed.

F. The displacement power factor of the VSMC shall not be less than 95 percent under any speed or load condition.

G. VSMC current and voltage harmonic distortion shall not exceed the values allowed by IEEE 519.

H. VSMC shall have the following features:

1. Isolated power for control circuits.

2. Manually resettable overload protection for each phase.

3. Adjustable current limiting circuitry to provide soft motor starting. Maximum starting current shall not exceed 200 percent of motor full load current.
4. Independent acceleration and deceleration time adjustment, manually adjustable from 2 to 2000 seconds. Set timers to the equipment manufacturer's recommended time in the above range.
5. Control input circuitry that will accept 4 to 20 mA current or 0-10 VDC voltage control signals from an external source.
6. Automatic frequency adjustment from 1 Hz to 300 Hz.
7. Circuitry to initiate an orderly shutdown when any of the conditions listed below occur. The VSMC shall not be damaged by any of these electrical disturbances and shall automatically restart when the conditions are corrected. The VSMC shall be able to restart into a rotating motor operating in either the forward or reverse direction and matching that frequency.
 - a. Incorrect phase sequence.
 - b. Single phasing.
 - c. Overvoltage in excess of 10 percent.
 - d. Undervoltage in excess of 15 percent.
 - e. Running overcurrent above 110 percent (VSMC shall not automatically reset for this condition.)
 - f. Instantaneous overcurrent above 150 percent (VSMC shall not automatically reset for this condition).
 - g. Short duration power outages of 12 cycles or less (i.e., distribution line switching, generator testing, and automatic transfer switch operations.)
8. Power-Interruption Protection: To prevent motor from re-energizing after a power interruption until motor has stopped, unless "Bidirectional Autospeed Search" feature is available and engaged.
- I. VSMC shall include an input circuit breaker which will disconnect all input power, interlocked with the door so that the door cannot be opened with the circuit breaker in the closed position.
- J. VSMC shall include a 5% line reactor and a RFI/EMI filter.
- K. Surge Suppression: Provide three-phase protection against damage from supply voltage surges in accordance with UL 1449.
- L. VSMC shall include front-accessible operator station, with sealed keypad and digital display, which allows complete programming, operating, monitoring, and diagnostic capabilities.

1. Typical control functions shall include but not be limited to:
 - a. HAND-OFF-AUTOMATIC-RESET, with manual speed control in HAND mode.
 - b. NORMAL-BYPASS.
 - c. NORMAL-TEST, which allows testing and adjusting of the VSMC while in bypass mode.
2. Typical monitoring functions shall include but not be limited to:
 - a. Output frequency (Hz).
 - b. Motor speed and status (run, stop, fault).
 - c. Output voltage and current.
3. Typical fault and alarm functions shall include but not be limited to:
 - a. Loss of input signal, under- and over-voltage, inverter overcurrent, motor overload, critical frequency rejection with selectable and adjustable deadbands, instantaneous line-to-line and line-to-ground overcurrent, loss-of-phase, reverse-phase, and short circuit.
 - b. System protection indicators indicating that the system has shutdown and will not automatically restart.
- M. VSMC shall include two N.O. and two N.C. dry contacts rated 120 Volts, 10 amperes, 60 Hz.
- N. Hardware, software, network interfaces, gateways, and programming to control and monitor the VSMC by control systems specified in other specification sections, including but not limited to Divisions 22 and 23.
- O. Network communications ports: As required for connectivity to control systems specified in other specification sections, including but not limited to Divisions 22 and 23.
- P. Communications protocols: As required for communications with control systems specified in other specification sections, including but not limited to Divisions 22 and 23.
- Q. Bypass controller: Provide contactor-style bypass, arranged to bypass the inverter.
 1. Inverter Output Contactor and Bypass Contactor: Load-break NEMA-rated contactor.
 2. Motor overload relays.
 3. HAND-OFF-AUTOMATIC bypass control.
- R. Bypass operation: Transfers motor between inverter output and bypass circuit, manually, automatically, or both. VSMC shall be capable of

stable operation (starting, stopping, and running), and control by fire alarm and detection systems, with motor completely disconnected from the inverter output. Transfer between inverter and bypass contactor and retransfer shall only be allowed with the motor at zero speed.

- S. Inverter Isolating Switch: Provide non-load-break switch arranged to isolate inverter and permit safe troubleshooting and testing of the inverter, both energized and de-energized, while motor is operating in bypass mode. Include padlockable, door-mounted handle mechanism.

PART 3 - EXECUTION

3.1 INSTALLATION

- A. Install motor controllers in accordance with the NEC, as shown on the drawings, and as recommended by the manufacturer.
- B. Install manual motor controllers in flush enclosures in finished areas.
- C. Set field-adjustable switches, auxiliary relays, time-delay relays, timers, and electronic overload relay pickup and trip ranges.
- D. Program variable speed motor controllers per the manufacturer's instructions and in coordination with other trades so that a complete and functional system is delivered.
- E. Adjust trip settings of circuit breakers and motor circuit protectors with adjustable instantaneous trip elements. Initially adjust at six times the motor nameplate full-load ampere ratings and attempt to start motors several times, allowing for motor cooldown between starts. If tripping occurs on motor inrush, adjust settings in increments until motors start without tripping. Do not exceed eight times the motor full-load amperes (or 11 times for NEMA Premium Efficiency motors if required). Where these maximum settings do not allow starting of a motor, notify COR before increasing settings.

3.2 ACCEPTANCE CHECKS AND TESTS

- A. Perform manufacturer's required field tests in accordance with the manufacturer's recommendations. In addition, include the following:
 - 1. Visual Inspection and Tests:
 - a. Compare equipment nameplate data with specifications and approved shop drawings.
 - b. Inspect physical, electrical, and mechanical condition.
 - c. Verify appropriate anchorage, required area clearances, and correct alignment.
 - d. Verify that circuit breaker, motor circuit protector, and fuse sizes and types correspond to approved shop drawings.

- e. Verify overload relay ratings are correct.
- f. Vacuum-clean enclosure interior. Clean enclosure exterior.
- g. Verify tightness of accessible bolted electrical connections by calibrated torque-wrench method in accordance with manufacturer's published data.
- h. Test all control and safety features of the motor controllers.
- i. For low-voltage variable speed motor controllers, final programming and connections shall be by a factory-trained technician. Set all programmable functions of the variable speed motor controllers to meet the requirements and conditions of use.

3.3 FOLLOW-UP VERIFICATION

- A. Upon completion of acceptance checks, settings, and tests, the Contractor shall show by demonstration in service that the motor controllers are in good operating condition and properly performing the intended functions.

3.4 SPARE PARTS

- A. Two weeks prior to the final inspection, provide one complete set of spare fuses for each motor controller.

3.5 INSTRUCTION

- A. Furnish the services of a factory-trained technician for two 4-hour training periods for instructing personnel in the maintenance and operation of the motor controllers, on the dates requested by the COR.

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