SECTION 26 29 11
MOTOR STARTERS

PART 1 - GENERAL

1.1 DESCRIPTION

A. All motor starters and variable speed motor controllers, including installation and connection (whether furnished with the equipment specified in other Divisions or otherwise), shall meet these specifications.

1.2 RELATED WORK

A. Other sections which specify motor driven equipment, except elevator motor controllers.

B. Section 26 05 11, REQUIREMENTS FOR ELECTRICAL INSTALLATIONS: General electrical requirements and items that are common to more than one Section of Division 26.

C. Section 26 05 26, GROUNDING AND BONDING FOR ELECTRICAL SYSTEMS: Requirements for personnel safety and to provide a low impedance path for possible ground fault currents.

1.3 QUALITY ASSURANCE

A. Refer to Paragraph, QUALIFICATIONS, in Section 26 05 11, REQUIREMENTS FOR ELECTRICAL INSTALLATIONS.

1.4 SUBMITTALS

A. Submit in accordance with Section 26 05 11, REQUIREMENTS FOR ELECTRICAL INSTALLATIONS:

B. Shop Drawings:

1. Sufficient information, clearly presented, shall be included to determine compliance with drawings and specifications.
2. Include electrical ratings, dimensions, weights, mounting details, materials, running over current protection, size of enclosure, over current protection, wiring diagrams, starting characteristics, interlocking and accessories.

C. Manuals:

1. Submit, simultaneously with the shop drawings, companion copies of complete maintenance and operating manuals, including technical data sheets, wiring diagrams and information for ordering replacement parts.
   a. Wiring diagrams shall have their terminals identified to facilitate installation, maintenance and operation.
   b. Wiring diagrams shall indicate internal wiring for each item of equipment and interconnections between the items of equipment.

c. Elementary schematic diagrams shall be provided for clarity of operation.

2. Two weeks prior to the project final inspection, submit four copies of the final updated maintenance and operating manual to the COTR.

D. Certification: Two weeks prior to final inspection, unless otherwise noted, submit four copies of the following certifications to the Resident Engineer:

1. Certification that the equipment has been properly installed, adjusted, and tested.
2. Certification by the manufacturer that medium voltage motor controller(s) conforms to the requirements of the drawings and specifications. This certification must be furnished to the Resident Engineer prior to shipping the controller(s) to the job site.

1.5 APPLICABLE PUBLICATIONS

A. Publications listed below (including amendments, addenda, revisions, supplements and errata) form a part of this specification to the extent referenced. Publications are referenced in the text by basic designation only.

B. Institute of Electrical and Electronic Engineers (IEEE):

519.....Recommended Practices and Requirements for Harmonic Control in Electrical Power Systems

C37.90.1.....Standard Surge Withstand Capability (SWC) Tests for Protective Relays and Relay Systems

C. National Electrical Manufacturers Association (NEMA):

ICS 1.....Industrial Control and Systems General Requirements

ICS 1.1.....Safety Guidelines for the Application, Installation and Maintenance of Solid State Control

ICS 2.....Industrial Control and Systems, Controllers, Contactors and Overload Relays Rated 600 Volts DC

ICS 6.....Industrial Control and Systems Enclosures

ICS 7.....Industrial Control and Systems Adjustable-Speed Drives

ICS 7.1.....Safety Standards for Construction and Guide for Selection, Installation and Operation of Adjustable-Speed Drive Systems

D. National Fire Protection Association (NFPA):

70.....National Electrical Code (NEC)

E. Underwriters Laboratories Inc. (UL):
508.....Industrial Control Equipment

PART 2 - PRODUCTS

2.1 MOTOR STARTERS, GENERAL

A. Shall be in accordance with the requirements of the IEEE, NEC, NEMA (ICS 1, ICS 1.1, ICS 2, ICS 6, ICS 7 and ICS 7.1) and UL.

B. Shall have the following features:

1. Separately enclosed unless part of another assembly.
2. Circuit breakers and safety switches within the motor controller enclosures shall have external operating handles with lock-open padlocking provisions and shall indicate the ON and OFF positions.
3. Motor control circuits:
   a. Shall operate at not more than 120 volts.
   b. Shall be grounded except as follows:
      1) Where isolated control circuits are shown.
      2) Where manufacturers of equipment assemblies recommend that the control circuits be isolated.
   c. Incorporate a separate, heavy duty, control transformer within each motor controller enclosure to provide the control voltage for each motor operating over 120 volts.
   d. Incorporate over current protection for both primary and secondary windings of the control power transformers in accordance with the NEC.
4. Overload current protective devices:
   a. Overload relay (thermal or induction type.
   b. One for each pole.
   c. Manual reset on the door of each motor controller enclosure.
   d. Correctly sized for the associated motor's rated full load current.
   e. Check every motor controller after installation and verify that correct sizes of protective devices have been installed.
   f. Deliver four copies of a summarized list to the Resident Engineer, which indicates and adequately identifies every motor controller installed. Include the catalog numbers for the correct sizes of protective devices for the motor controllers.
5. Hand-Off-Automatic (H-O-A) switch is required unless specifically stated on the drawings as not required for a particular starter. H-O-A switch is not required for manual motor starters.

6. Incorporate into each control circuit a 120-volt, solid state time delay relay (ON delay), minimum adjustable range from 0.3 to 10 minutes, with transient protection. Time delay relay is not required where H-O-A switch is not required.
7. Unless noted otherwise, equip with not less than two normally open and two normally closed auxiliary contacts. Provide green run pilot lights and H-O-A control devices as indicated, operable at front of enclosure without opening enclosure. Push buttons, selector switches, pilot lights, etc., shall be interchangeable.
8. Enclosures:
   a. Shall be the NEMA types shown on the drawings for the motor controllers and shall be the NEMA types which are the most suitable for the environmental conditions where the motor controllers are being installed.
   b. Doors mechanically interlocked to prevent opening unless the breaker or switch within the enclosure is open. Provision for padlock must be provided.
   c. Enclosures shall be primed and finish coated at the factory with the manufacturer’s prime coat and standard finish.

C. Motor controllers incorporated with equipment assemblies shall also be designed for the specific requirements of the assemblies.

D. Additional requirements for specific motor controllers, as indicated in other sections, shall also apply.

E. Provide a disconnecting means or safety switch near and within sight of each motor. Provide all wiring and conduit required to facilitate a complete installation.

2.2 MANUAL MOTOR STARTERS

A. Shall be in accordance with applicable requirements of 2.1 above.

B. Manual motor starters.
   1. Starters shall be general-purpose Class A, manually operated type with full voltage controller for induction motors, rated in horsepower.
   2. Units shall include overload protection, red pilot light, and toggle operator.

C. Fractional horsepower manual motor starters.
   1. Starters shall be general-purpose Class A, manually operated with full voltage controller for fractional horsepower induction motors.
   2. Units shall include thermal overload protection, red pilot light and toggle operator.

D. Motor starting switches.

1. Switches shall be general-purpose Class A, manually operated type with full voltage controller for fractional horsepower induction motors.
2. Units shall include thermal overload protection, red pilot light and toggle operator.

2.3 MAGNETIC MOTOR STARTERS

A. Shall be in accordance with applicable requirements of 2.1 above.

B. Starters shall be general-purpose, Class A magnetic controllers for induction motors rated in horsepower. Minimum size 0.

C. Where combination motor starters are used, combine starter with protective or disconnect device in a common enclosure.

D. Provide phase loss protection for each starter, with contacts to de-energize the starter upon loss of any phase.

E. Unless otherwise indicated, provide full voltage non-reversing across-the-line mechanisms for motors less than 75 HP, closed by coil action and opened by gravity. For motors 75 HP and larger, provide reduced voltage starters. Equip starters with 120V AC coils and individual control transformer unless otherwise noted. Locate "reset" button to be accessible without opening the enclosure.

2.4 VARIABLE SPEED MOTOR CONTROLLERS

A. Shall be in accordance with applicable portions of 2.1 above.

B. Shall be solid state, micro processor-based with adjustable frequency and voltage, three phase output capable of driving standard NEMA B design, three phase alternating current induction motors at full rated speed. The drives shall utilize a full wave bridge design incorporating diode rectifier circuitry with pulse width modulation (PWM). Other control techniques are not acceptable. Silicon controlled rectifiers (SCR) shall not be used in the rectifying circuitry. The drives shall be designed to be used on variable torque loads and shall be capable of providing sufficient torque to allow the motor to break away from rest upon first application of power.

C. Unit shall be capable of operating within voltage parameters of plus 10 to minus 10 percent of line voltage, and be suitably rated for the full load amps of the maximum watts (HP) within its class.

D. Operating and Design Conditions:

Elevation: Check local conditions for feet AMSL.

Temperatures: Maximum +90°F Minimum -10°F.

Relative Humidity: 95%.

Drive Location: As shown on drawings.

E. Controllers shall have the following features:
   1. Isolated power for control circuits.
   2. Manually re-settable motor overload protection for each phase.
   3. Adjustable current limiting circuitry to provide soft motor starting. Maximum starting current shall not exceed 200 percent of motor full load current.
   4. Independent acceleration and deceleration time adjustment, manually adjustable from 2 to 30 seconds. (Set timers to the equipment manufacturer's recommended time in the above range.)
   5. Provide 4 to 20 ma current follower circuitry for interface with mechanical sensor devices.
   6. Automatic frequency adjustment from 20 Hz to 60 Hz.
   7. Provide circuitry to initiate an orderly shutdown when any of the conditions listed below occur. The controller shall not be damaged by any of these electrical disturbances and shall automatically restart when the conditions are corrected. The drive shall be able to restart into a rotating motor operating in either the forward or reverse direction and matching that frequency.
      a. Incorrect phase sequence.
      b. Single phasing.
      c. Over voltage in excess of 10 percent.
      d. Under voltage in excess of 10 percent.
      e. Running over current above 110 percent (shall not automatically reset for this condition.)
      f. Instantaneous overcurrent above 150 percent (shall not automatically reset for this condition).
      g. Surge voltage in excess of 1000 volts.
      h. Short duration power outages of 12 cycles or less (i.e., distribution line switching, generator testing, and automatic transfer switch operations.)
   8. Automatic Reset/Restart: Attempt three restarts after drive fault or on return of power after an interruption and before shutting down for manual reset or fault correction; adjustable delay time between restart attempts.
   9. Bidirectional Autospeed Search: Capable of starting VFC into rotating loads spinning in either direction and returning motor to set speed in proper direction, without causing damage to drive, motor, or load.

F. Minimum efficiency shall be 95 percent at 100 percent speed and 85percent at 50 percent speed.

G. The displacement power factor of the controller shall not be less than 95 percent under any speed or load condition.

H. Controllers shall include a door interlocked fused safety disconnect switch or door interlocked circuit breaker switch which will disconnect all input power.

I. Controller shall include a 3% line reactor, and RFI/EMI filter.

J. The following accessories are to be door mounted:

1. AC Power on light.
2. Ammeter (RMS motor current).
3. HAND-OFF-AUTOMATIC switch.
4. Manual speed control in HAND mode.
5. System protection lights indicating that the system has shutdown and will not automatically restart.
6. System protection light indicating that the system has shutdown but will restart when conditions return to normal.
7. Manual variable speed controller by-pass switch.
8. Diagnostic shutdown indicator lights for each shutdown condition.
9. Provide two N.O. and two N.C. dry contacts rated 120 volts, 10 amperes, 60 HZ for remote indication of the following:
   a. System shutdown with auto restart.
   b. System shutdown without auto restart.
   c. System running.
10. Incorporate into each control circuit a 120-volt, time delay relay (ON delay), adjustable from 0.3-10 minutes, with transient protection. Provide transformer/s for the control circuit/s.
11. Controller shall not add any current or voltage transients to the input AC power distribution system nor shall transients from other devices on the AC power distribution system affect the controller. Controllers shall be protected to comply with IEEE C37.90.1 and UL-508. Line noise and harmonic voltage distortion shall not exceed the values allowed by IEEE 519.

K. Hardware and software to enable the BAS to monitor, control, and display controller status and alarms.

L. Network Communications Ports: Ethernet and RS-422 or 485 per control system requirements. Verify with COTR or EC&D (VA’s control system contractor.

M. Embedded BAS Protocols for Network Communications: As specified in Division 22.

N. Bypass Operation: Manually transfers motor between power converter output and bypass circuit, manually, automatically, or both. Unit is capable of stable operation (starting, stopping, and running) with motor completely disconnected from power converter. Transfer between power converter and bypass contactor and retransfer shall only be allowed with the motor at zero speed.

PART 3 - EXECUTION

3.1 INSTALLATION

A. Install motor control equipment in accordance with manufacturer's recommendations, the NEC, NEMA and as shown on the drawings.

B. Furnish and install heater elements in motor starters and to match the installed motor characteristics. Submit a list of all motors listing motor nameplate rating and heater element installed.

C. Motor Data: Provide neatly-typed label inside each motor starter enclosure door identifying motor served, nameplate horsepower, full load amperes, code letter, service factor, voltage/phase rating and heater element installed.

D. Connect hand-off auto selector switches so that automatic control only is by-passed in "manual" position and any safety controls are not by-passed.

E. Install manual motor starters in flush enclosures in finished areas.

F. Examine control diagrams indicated before ordering motor controllers. Should conflicting data exist in specifications, drawings and diagrams, request corrected data prior to placing orders.

3.2 ADJUSTING

A. Set field-adjustable switches, auxiliary relays, time-delay relays, timers, and overload-relay pickup and trip ranges.

B. Adjust overload-relay heaters or settings if power factor correction capacitors are connected to the load side of the overload relays.

C. Adjust trip settings of MCPs and thermal-magnetic circuit breakers with adjustable instantaneous trip elements. Initially adjust at six times the motor nameplate full-load ampere ratings and attempt to start motors several times, allowing for motor cooldown between starts. If tripping occurs on motor inrush, adjust settings in increments until motors start without tripping. Do not exceed eight times the motor full-load amperes (or 11 times for NEMA Premium Efficient motors if required). Where these maximum settings do not allow starting of a motor, notify Resident Engineer before increasing settings.

3.3 ACCEPTANCE CHECKS AND TESTS

A. Perform in accordance with the manufacturer's recommendations. Include the following visual and mechanical inspections and electrical tests:

1. Visual and Mechanical Inspection:
   a. Compare equipment nameplate data with specifications and approved shop drawings.
   b. Inspect physical, electrical, and mechanical condition.
   c. Inspect contactors.
   d. Clean motor starters and variable speed motor controllers.
   e. Verify overload element ratings are correct for their applications.
   f. If motor-running protection is provided by fuses, verify correct fuse rating.
   g. Verify tightness of accessible bolted electrical connections by calibrated torque-wrench method in accordance with manufacturer’s published data.
2. Variable speed motor controllers:
   a. Final programming and connections to variable speed motor controllers shall be by a factory-trained technician. Set all programmable functions of the variable speed motor controllers to meet the requirements and conditions of use.
   b. Test all control and safety features of the variable frequency drive.

3.4 FOLLOW-UP VERIFICATION

A. Upon completion of acceptance checks, settings, and tests, the Contractor shall show by demonstration in service that the motor starters and variable speed motor controllers are in good operating condition and properly performing the intended functions.

3.5 SPARE PARTS

A. Two weeks prior to the final inspection, provide one complete set of spare fuses (including heater elements) for each starter/controller installed on this project.

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