

SECTION 23 09 23

DIRECT-DIGITAL CONTROL SYSTEM FOR HVAC

PART 1 - GENERAL

1.1 DESCRIPTION

A. The control system(s) shall be an ***extension of the existing Johnson Control Metasys System*** as indicated in the project documents and specifications. This scope of work shall include a complete and working system including all engineering, programming, controls and installation materials, installation labor, commissioning and start-up, training, final project documentation and warranty.

B. ***All control work shall be performed by Johnson Controls, Inc Windsor, CT 06095 without exception. The contact for this system is Jeff Hines (860-882-7082).*** Failure to use specified manufacturer for products and installation will result in any and all rework performed at the contractor's expense including labor and materials.

C. All work is to be installed with ***Johnson Controls BACnet MS/TP Open Protocol*** products and integrated into the existing Johnson Controls Metasys Extended Architecture ADX Application Data Server through the existing IT Infrastructure. Johnson Controls FX Products are not acceptable as these products are not covered in the Johnson Controls VA West Haven Service contract and the facilities maintenance staff is not familiar with these products.

D. The Controls Contractor's work shall include all labor, materials, special tools, equipment, enclosures, power supplies, software, software licenses, Project specific software configurations and database entries, interfaces, wiring, tubing, installation, labeling, engineering, calibration, documentation, submittals, testing, verification, training services, permits and licenses, transportation, shipping, handling, administration, supervision, management, insurance, Warranty, specified services and items required by the Contract for the complete and fully functional Controls Systems.

E. Following control devices and systems shall be used to provide the functional requirements of HVAC equipment and systems.

1. Direct Digital Control (DDC) of HVAC equipment and systems with electric or electronic positioning of valves and dampers.

2. Terminal units including VAV Boxes, Fan Powered Boxes, Unit Heaters, Cabinet Unit Heaters, Fan Coil Units, Base Board Heaters, Secondary Humidifiers and similar units for control of room environment conditions may be equipped with integral controls furnished and installed by the equipment manufacturer or field mounted. Refer to equipment specifications and as indicated in project documents.

F. Base bid includes the installation of new DDC controls as well as electronic operators as indicated on the temperature control diagrams and the I/O Points List.

G. Connect the new work to the existing ECC operator workstation manufactured located in the facilities office. The existing operator workstation will be used to interface with the system. New systems including interface to existing systems and equipment shall operate and function as one

complete system including one database of control point objects and global control logic capabilities. Facility operators shall have complete operations and control capability over all systems, new and existing including; monitoring, trending, graphing, scheduling, alarm management, global point sharing, global strategy deployment, graphical operations interface and custom reporting as specified. Modify the existing ECC, if necessary, to accommodate the additional control points.

H. The control subcontractor shall supply as required, all necessary hardware equipment and software packages to interface between any existing and new system Network Control Units (NCU) as part of this contract. Number of area controllers required is dependent on the type and quantity of devices, hardware and software points provided.

I. The control systems shall be designed such that each mechanical system shall operate under stand-alone mode. Temperature Controls contractor shall provide controllers for each mechanical system. In the event of a network communication failure, or the loss of any other controller, the control system shall continue to operate independently. Failure of the ECC shall have no effect on the field controllers, including those involved with global strategies.

J. The Top End of the Network Automation Engine network controller shall communicate with the BACnet IP protocol.

K. Power wiring shall not be run in conduit with communications trunk wiring or signal or control wiring operating at 100 volts or less.

L. The control system shall accommodate 5 users simultaneously, and the access to the system should be limited only by operator password.

1.2 RELATED WORK

- A. Section 28 31 00, FIRE DETECTION AND ALARM.
- B. Section 23 05 11, COMMON WORK RESULTS FOR HVAC AND STEAM GENERATION.
- C. Section 22 62 00, VACUUM SYSTEMS FOR LABORATORY AND HEALTHCARE FACILITIES and Section 22 63 00, GAS SYSTEMS FOR LABORATORY AND HEALTHCARE FACILITIES.
- D. Section 21 10 00, WATER-BASED FIRE-SUPPRESSION SYSTEMS.
- E. Section 23 64 00, PACKAGED WATER CHILLERS.
- F. Section 23 21 13, HYDRONIC PIPING and Section 23 22 13, STEAM AND CONDENSATE HEATING PIPING.
- G. Section 23 36 00, AIR TERMINAL UNITS.
- H. Section 23 73 00, INDOOR CENTRAL-STATION AIR-HANDLING UNITS.
- I. Section 23 74 13, PACKAGED, OUTDOOR, CENTRAL-STATION AIR-HANDLING UNITS.
- J. Section 23 31 00, HVAC DUCTS AND CASINGS.
- K. Section 23 09 11, INSTRUMENTATION AND CONTROL FOR BOILER PLANT.
- L. Section 23 05 93, TESTING, ADJUSTING, AND BALANCING FOR HVAC.
- M. Section 26 05 11, REQUIREMENTS FOR ELECTRICAL INSTALLATIONS.
- N. Section 26 05 33, RACEWAY AND BOXES FOR ELECTRICAL SYSTEMS.
- O. Section 26 05 21, LOW-VOLTAGE ELECTRICAL POWER CONDUCTORS AND CABLES (600 VOLTS AND BELOW).
- P. Section 26 27 26, WIRING DEVICES.
- Q. Section 26 32 13, ENGINE GENERATORS.

1.3 DEFINITION

- A. Algorithm: A logical procedure for solving a recurrent mathematical

problem; A prescribed set of well-defined rules or processes for the solution of a problem in a finite number of steps.

B. ACU: Auxiliary Control Unit (ACU) used for controls of air handling units, reports to RCU.

C. Analog: A continuously varying signal value (e.g., temperature, current, velocity etc).

D. BACnet: Building Automation Control Network Protocol, ASHRAE Standard 135.

E. Baud: It is a signal change in a communication link. One signal change can represent one or more bits of information depending on type of transmission scheme. Simple peripheral communication is normally one bit per Baud. (e.g., Baud rate = 78,000 Baud/sec is 78,000 bits/sec, if one signal change = 1 bit).

F. Binary: A two-state system where a high signal level represents an "ON" condition and an "OFF" condition is represented by a low signal level.

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G. BMP or bmp: Suffix, computerized image file, used after the period in a DOS-based computer file to show that the file is an image stored as a series of pixels.

H. Bus Topology: A network topology that physically interconnects workstations and network devices in parallel on a network segment.

I. Control Unit (CU): Generic term for any controlling unit, stand-alone, microprocessor based, digital controller residing on secondary LAN or Primary LAN, used for local controls or global controls. In this specification, there are three types of control units are used; Unitary Control Unit (UCU), Auxiliary Control Unit (ACU), and Remote Control Unit (RCU).

J. Deadband: A temperature range over which no heating or cooling is supplied, i.e., 22-25 degrees C (72-78 degrees F), as opposed to a single point change over or overlap).

K. Diagnostic Program: A software test program, which is used to detect and report system or peripheral malfunctions and failures. Generally, this system is performed at the initial startup of the system.

L. Direct Digital Control (DDC): Microprocessor based control including Analog/Digital conversion and program logic. A control loop or subsystem in which digital and analog information is received and processed by a microprocessor, and digital control signals are generated based on control algorithms and transmitted to field devices in order to achieve a set of predefined conditions.

M. Distributed Control System: A system in which the processing of system data is decentralized and control decisions can and are made at the subsystem level. System operational programs and information are provided to the remote subsystems and status is reported back to the Engineering Control Center. Upon the loss of communication with the Engineering Control center, the subsystems shall be capable of operating in a stand-alone mode using the last best available data.

N. Download: The electronic transfer of programs and data files from a central computer or operation workstation with secondary memory devices to remote computers in a network (distributed) system.

O. Electrical Control: A control circuit that operates on line or low voltage and uses a mechanical means, such as a temperature sensitive bimetal or bellows, to perform control functions, such as actuating a switch or positioning a potentiometer.

P. Electronic Control: A control circuit that operates on low voltage and uses a solid-state components to amplify input signals and perform control functions, such as operating a relay or providing an output signal to position an actuator.

Q. Engineering Control Center (ECC): The centralized control point for the intelligent control network. The ECC comprises of personal computer and connected devices to form a single workstation.

R. Ethernet: A trademark for a system for exchanging messages between computers on a local area network using coaxial, fiber optic, or twisted-pair cables.

S. Firmware: Firmware is software programmed into read only memory (ROM) chips. Software may not be changed without physically altering the chip.

T. FTT-10: Echelon Transmitter-Free Topology Transceiver.

U. GIF: Abbreviation of Graphic interchange format.

V. Graphic Program (GP): Program used to produce images of air handler systems, fans, chillers, pumps, and building spaces. These images can be animated and/or color-coded to indicate operation of the equipment.

W. Graphic Sequence of Operation: It is a graphical representation of the sequence of operation, showing all inputs and output logical blocks.

X. I/O Unit: The section of a digital control system through which information is received and transmitted. I/O refers to analog input (AI, digital input (DI), analog output (AO) and digital output (DO). Analog signals are continuous and represent temperature, pressure, flow rate etc, whereas digital signals convert electronic signals to digital pulses (values), represent motor status, filter status, on-off equipment etc.

Y. I/P: Internet Protocol-global network, connecting workstations and other host computers, servers etc. to share the information.

Z. JPEG: A standardized image compression mechanism stands for Joint Photographic Experts Group, the original name of the committee that wrote the standard.

AA. Local Area Network (LAN): A communication bus that interconnects operator workstation and digital controllers for peer-to-peer communications, sharing resources and exchanging information.

BB. Network: A set of computers or other digital devices communicating with each other over a medium such as wire, coax, fiber optics cable etc.

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CC. Network Area Controller: Digital controller, supports a family of auxiliary control units and unitary control units, and communicates with peer-to-peer network for transmission of global data.

DD. Network Repeater: A device that receives data packet from one network and rebroadcasts to another network. No routing information is added to the protocol.

EE. MS/TP: Master-slave/token-passing.

FF. Operating system (OS): Software, which controls the execution of computer application programs.

GG. PCX: File type for an image file. When photographs are scanned onto a personal computer they can be saved as PCX files and viewed or changed by a special application program as Photo Shop.

HH. Peripheral: Different components that make the control system function as one unit. Peripherals include monitor, printer, and I/O unit.

II. Peer-to-Peer: A networking architecture that treats all network stations as equal partners.

JJ. PICS: Protocol Implementation Conformance Statement.

KK. UCU: Unitary Control Unit, digital controller, dedicated to a specific piece of equipment, such as VAV boxes, chillers, fan coil units, heat exchangers etc.

1.4 QUALITY ASSURANCE

A. Criteria:

1. The Controls and Instrumentation System Contractor shall be a primary equipment manufacturer-owned branch office that is regularly engaged in the engineering, programming, installation and service of total integrated Facility Management Systems of similar size, scope and complexity to the EEC specified in this Contract. Distributors, manufacturer's representatives and wholesalers will not be acceptable.

2. Single Source Responsibility of subcontractor: The Contractor shall obtain hardware and software supplied under this Section and delegates the responsibility to a single source controls installation subcontractor. The controls subcontractor shall be responsible for the complete design, installation, and commissioning of the system. The controls subcontractor shall be in the business of design, installation and service of such building automation control systems similar in size and complexity.

3. Equipment and Materials: Equipment and materials shall be cataloged products of manufacturers regularly engaged in production and installation of HVAC control systems. Products shall be manufacturer's latest standard design and have been tested and proven in actual use.

4. The controls subcontractor shall provide a list of no less than five similar projects which have building control systems as specified in this Section. These projects must be on-line and functional such that the Department of Veterans Affairs (VA) representative would observe the control systems in full operation.

5. The controls subcontractor shall have (minimum of three years) experience in design and installation of building automation systems similar in performance to those specified in this Section. Provide evidence of experience by submitting resumes of the project manager, the local branch manager, project engineer, the application engineering staff, and the electronic technicians who would be involved with the supervision, the engineering, and the installation of the control systems. Training and experience of these personnel shall not be less than three years. Failure to disclose this information will be a ground for disqualification of the supplier.

6. The controls subcontractor shall have in-place facility within 50 miles with technical staff, spare parts inventory for the next five (5) years, and necessary test and diagnostic equipment to support the control systems.

7. Provide a competent and experienced Project Manager employed by the Controls Contractor. The Project Manager shall be supported as necessary by other Contractor employees in order to provide professional engineering, technical and management service for the work. The Project Manager shall attend scheduled Project Meetings as

required and shall be empowered to make technical, scheduling and related decisions on behalf of the Controls Contractor.

B. Codes and Standards:

1. All work shall conform to the applicable Codes and Standards.
2. Electronic equipment shall conform to the requirements of FCC Regulation, Part 15, Governing Radio Frequency Electromagnetic Interference, and be so labeled.
3. Peer-to-peer controllers, unitary controllers shall conform to the requirements of UL 916, Category PAZX.

1.5 PERFORMANCE

A. The system shall conform to the following:

1. Graphic Display: The system shall display up to 4 graphics on a single screen with a minimum of (20) dynamic points per graphic. All current data shall be displayed within (10) seconds of the request.
2. Graphic Refresh: The system shall update all dynamic points with current data within (10) seconds. Data refresh shall be automatic, without operator intervention.
3. Object Command: The maximum time between the command of a binary object by the operator and the reaction by the device shall be (10) seconds. Analog objects shall start to adjust within (3) seconds.
4. Object Scan: All changes of state and change of analog values shall be transmitted over the high-speed network such that any data used or displayed at a controller or work-station will be current, within the prior (10) seconds.
5. Alarm Response Time: The maximum time from when an object goes into alarm to when it is annunciated at the workstation shall not exceed (10) seconds.
6. Program Execution Frequency: Custom and standard applications shall be capable of running as often as once every (5) seconds. The Contractor shall be responsible for selecting execution times consistent with the mechanical process under control.
7. Performance: Programmable Controllers shall be able to execute DDC PID control loops at a selectable frequency from at least once every five (5) seconds. The controller shall scan and update the process value and output generated by this calculation at this same frequency.
8. Multiple Alarm Annunciations: All workstations on the network shall receive alarms within (5) seconds of each other.
9. Reporting Accuracy: Listed below are minimum acceptable reporting accuracies for all values reported by the specified system:

Measured Variable Reported Accuracy

Space temperature ± 0.5 degrees C (± 1 degrees F)
Ducted air temperature ± 1.0 degrees C [± 2 degrees F]
Outdoor air temperature ± 1.0 degrees C [± 2 degrees F]
Water temperature ± 0.5 degrees C [± 1 degrees F]
Relative humidity ± 2 percent RH
Water flow ± 5 percent of full scale
Air flow (terminal) ± 10 percent of reading
Air flow (measuring stations)
 ± 5 percent of reading
Air pressure (ducts) ± 25 Pa [± 0.1 "W.G.]
Air pressure (space) ± 3 Pa [± 0.001 "W.G.]
Water pressure ± 2 percent of full scale *Note 1
Electrical Power 5 percent of reading

Note 1: for both absolute and differential pressure

1.6 WARRANTY

A. Labor and materials for control systems shall be warranted for a period as specified under Warranty in FAR clause 52.246-21.

B. Control system failures during the warranty period shall be adjusted, repaired, or replaced at no cost or reduction in service to the owner. The system includes all computer equipment, transmission equipment, and all sensors and control devices.

C. The on-line support service shall allow the Controls supplier to dial out over telephone lines to monitor and control the facility's building automation system. This remote connection to the facility shall be within two (2) hours of the time that the problem is reported. This coverage shall be extended to include normal business hours, after business hours, weekend and holidays. If the problem cannot be resolved with on-line support services, the Controls supplier shall dispatch the qualified personnel to the job site to resolve the problem within 24 hours after the problem is reported.

D. Controls and Instrumentation subcontractor shall be responsible for temporary operations and maintenance of the control systems during the construction period until final commissioning, training of facility operators and acceptance of the project by VA.

1.7 SUBMITTALS

A. Submit shop drawings in accordance with Section 01 33 23, SHOP DRAWINGS, PRODUCT DATA, AND SAMPLES.

B. Manufacturer's literature and data for all components including the following:

1. A wiring diagram for each type of input device and output device including DDC controllers, modems, repeaters, etc. Diagram shall show how the device is wired and powered, showing typical connections at the digital controllers and each power supply, as well as the device itself. Show for all field connected devices, including but not limited to, control relays, motor starters, electric or electronic actuators, and temperature pressure, flow and humidity sensors and transmitters.
2. A diagram of each terminal strip, including digital controller terminal strips, terminal strip location, termination numbers and the associated point names.
3. Control dampers and control valves schedule, including the size and pressure drop.
4. Installation instructions for smoke dampers and combination smoke/fire dampers, if furnished.
5. Control air-supply components, and computations for sizing compressors, receivers and main air-piping, if pneumatic controls are furnished.
6. Catalog cut sheets of all equipment used. This includes, but is not limited to DDC controllers, panels, peripherals, airflow measuring stations and associated components, and auxiliary control devices such as sensors, actuators, and control dampers. When manufacturer's cut sheets apply to a product series rather than a specific product, the data specifically applicable to the project shall be highlighted. Each submitted piece of literature and drawings should

clearly reference the specification and/or drawings that it supposed to represent.

7. Sequence of operations for each HVAC system and the associated control diagrams. Equipment and control labels shall correspond to those shown on the drawings.
8. Color prints of proposed graphics with a list of points for display.
9. Furnish PICS for each BACNET compliant device.

C. Product Certificates: Compliance with Article, QUALITY ASSURANCE.

D. As Built Control Drawings:

1. Furnish three (3) copies of as-built drawings for each control system. The documents shall be submitted for approval prior to final completion.
2. Furnish one (1) stick set of applicable control system prints for each mechanical system for wall mounting. The documents shall be submitted for approval prior to final completion.
3. Furnish one (1) CD-ROM in CAD DWG and/or .DXF format for the drawings noted in subparagraphs above.

E. Operation and Maintenance (O/M) Manuals):

1. Submit in accordance with Article, INSTRUCTIONS, in Specification Section 01 00 00, GENERAL REQUIREMENTS.
2. Include the following documentation:
 - a. General description and specifications for all components, including logging on/off, alarm handling, producing trend reports, overriding computer control, and changing set points and other variables.
 - b. Detailed illustrations of all the control systems specified for ease of maintenance and repair/replacement procedures, and complete calibration procedures.
 - c. One copy of the final version of all software provided including operating systems, programming language, operator workstation software, and graphics software.
 - d. Complete troubleshooting procedures and guidelines for all systems.
 - e. Complete operating instructions for all systems.
 - f. Recommended preventive maintenance procedures for all system components including a schedule of tasks for inspection, cleaning and calibration. Provide a list of recommended spare parts needed to minimize downtime.
 - g. Licenses, guaranty, and other pertaining documents for all equipment and systems.
 - h. Training Manuals: Submit the course outline and training material to the Owner for approval three (3) weeks prior to the training to VA facility personnel. These persons will be responsible for maintaining and the operation of the control systems, including programming. The Owner reserves the right to modify any or all of the course outline and training material.

F. Submit Performance Report to Resident Engineer prior to final inspection.

1.8 INSTRUCTIONS

A. Instructions to VA operations personnel: Perform in accordance with Article, INSTRUCTIONS, in Specification Section 01 00 00, GENERAL REQUIREMENTS, and as noted below.

1. First Phase: Formal instructions to the VA facilities personnel for a total of 8 hours, conducted sometime between the completed installation and prior to the performance test period of the control system, at a time mutually agreeable to the Contractor and the VA.
2. Second Phase: This phase of training shall comprise of on the job training during start-up, checkout period, and performance test period. VA facilities personnel will work with the Contractor's installation and test personnel on a daily basis during start-up and checkout period. During the performance test period, controls subcontractor will provide 16 hours of instructions to the VA facilities personnel.
3. The O/M Manuals shall contain approved submittals as outlined in Article 1.7, SUBMITTALS. The Controls subcontractor will review the manual contents with VA facilities personnel during second phase of training.
4. Training by independent or franchised dealers who are not direct employees of the controls supplier will not be acceptable.

1.9 PROJECT CONDITIONS (ENVIRONMENTAL CONDITIONS OF OPERATION)

- A. The ECC and peripheral devices and system support equipment shall be designed to operate in ambient condition of 20 to 35 degrees C (65 to 90 degrees F) at a relative humidity of 20 to 80 percent noncondensing.
- B. The CUs and associated equipment used in controlled environment shall be mounted in NEMA 1 enclosures for operation at 0 to 50 degrees C (32 to 122 degrees F) at a relative humidity of 10 to 90 percent noncondensing.
- C. The CUs used outdoors shall be mounted in NEMA 4 waterproof enclosures, and shall be rated for operation at -40 to 65 degrees C (-40 to 150 degrees F).
- D. All electronic equipment shall operate properly with power fluctuations of plus 10 percent to minus 15 percent of nominal supply voltage.
- E. Sensors and controlling devices shall be designed to operate in the environment, which they are sensing or controlling.

1.10 APPLICABLE PUBLICATIONS

- A. The publications listed below form a part of this specification to the extent referenced. The publications are referenced in the text by the basic designation only.
- B. American Society of Heating, Refrigerating, and Air-Conditioning Engineers (ASHRAE):
 - Standard 135-04.....BACNET Building Automation and Control Networks
- C. American Society of Mechanical Engineers (ASME):
 - B16.18-01.....Cast Copper Alloy Solder Joint Pressure Fittings.
 - B16.22-01.....Wrought Copper and Copper Alloy Solder Joint Pressure Fittings.
 - BPVC-CC-N-04.....Boiler and Pressure Vessel Code
- D. American Society of Testing Materials (ASTM):
 - B32-04.....Standard Specification for Solder Metal
 - B88-03.....Standard Specifications for Seamless Copper Water Tube
 - B88M-05.....Standard Specification for Seamless Copper Water Tube (Metric)
 - B280-03.....Standard Specification for Seamless Copper Tube for Air-Conditioning and Refrigeration Field Service
 - D2737-03.....Standard Specification for Polyethylene (PE) Plastic Tubing

E. Federal Communication Commission (FCC):
Rules and Regulations Title 47 Chapter 1-2001 Part 15..Radio Frequency
Devices.

F. Institute of Electrical and Electronic Engineers (IEEE):
802.3-05.....Information Technology-Telecommunications and
Information Exchange between Systems-Local and
Metropolitan Area Networks- Specific
Requirements-Part 3: Carrier Sense Multiple
Access with Collision Detection (CSMA/CD)
Access method and Physical Layer Specifications

G. Instrument Society of America (ISA):
7.0.01-1996.....Quality Standard for Instrument Air

H. National Fire Protection Association (NFPA):
70-05.....National Electric Code
90A-02.....Standard for Installation of Air-Conditioning
and Ventilation Systems

I. Underwriter Laboratories Inc (UL):
94-06.....Tests for Flammability of Plastic Materials for
Parts and Devices and Appliances
294-05.....Access Control System Units
486A/486B-04-.....Wire Connectors
555S-03.....Standard for Smoke Dampers
916-Rev 2-04.....Energy Management Equipment
1076-05.....Proprietary Burglar Alarm Units and Systems

PART 2 - PRODUCTS

2.1 CONTROLS SYSTEM ARCHITECTURE

A. General

1. The Controls Systems shall consist of multiple Nodes and associated equipment connected by industry standard digital and communication network arrangements.
2. The Operator Workstations, Servers and principal network computer equipment shall be standard products of recognized major manufacturers available through normal PC and computer vendor channels - not "Clones" assembled by a third-party subcontractor.
3. Provide licenses for all software residing on and used by the Controls Systems and transfer these licenses to the Owner prior to completion.
4. The networks shall, at minimum, comprise, as necessary, the following:
 - a. Operator Workstations - fixed and portable as required by the Specifications.
 - b. Network computer processing, data storage and communication equipment including Servers and digital data processors.
 - c. Routers, bridges, switches, hubs, modems, interfaces and the like communication equipment.
 - d. Active processing network area controllers connected to programmable field panels and controllers together with their power supplies and associated equipment.
 - e. Addressable elements, sensors, transducers and end devices.
 - f. Third-party equipment interfaces as required by the Contract Documents.
 - g. Other components required for a complete and working Control Systems integrated into the existing ECC as specified.

B. The Specifications for the individual elements and component subsystems shall be minimum requirements and shall be augmented as necessary by the Contractor to achieve both compliance with all applicable codes, standards and to meet all requirements of the Contract Documents.

C. Network Architecture

1. The Controls Systems Application network shall utilize an open architecture capable of each and all of the following:
 - a. Utilizing standard Ethernet communications and operate at a minimum speed of 10/100 Mb/sec.
 - b. Connecting via Johnson Controls MS/TP BACnet
2. The networks shall utilize only copper and optical fiber communication media as appropriate and shall comply with applicable codes, ordinances and regulations.
3. All necessary telephone lines, ISDN lines and internet Service Provider services and connections will be provided by the owner.
4. The Controls Contractor shall provide the IT interfacing equipment and shall coordinate on configuration and interfacing arrangements with the Data Cabling System contractor. The Controls Contractor shall coordinate IT equipment interfacing with the Data Cabling Systems contractor. This IT equipment shall be provided by the Data Cabling systems contractor directly at that contractor's cost. The Controls Contractor shall provide all IT interfacing equipment and cabling to a detail coordinated with the Owner.

D. Third Party Interfaces:

1. The Controls Systems shall include necessary hardware, equipment and software to allow data communications between the Controls Systems and building systems supplied by other trades.
2. The other manufacturers and contractors supplying other associated systems and equipment will provide their necessary hardware, software and start-up at their cost and will cooperate fully with the Controls Contractor in a timely manner and at their cost to ensure complete functional integration.

E. Servers:

1. Provide Controls Systems Application Server(s) to archive historical data including trends, alarm and event histories and transaction logs.
2. Equip these Server(s) with the same software Tool Set that is located in the Network Area Controllers for system configuration and custom logic definition and color graphic configuration.
3. Access to all information on the Controls Systems Server(s) shall be through the same browser Operator Interface functionality used to access individual nodes. When logged onto a Server the Operator will be able to also interact with any other NCUs on the Controls As required for the functional operation of the Controls Systems, the Controls Contractor shall provide all necessary digital processor programmable Server(s). These Server(s) shall be utilized for Controls Systems Application configuration, for archiving, reporting and trending of data, for Operator transaction archiving and reporting, for network information management, for alarm annunciation, for Operator Interface tasks, for Controls Application management and the like. These Server(s) shall utilize IT industry standard data base platforms such as Microsoft SQL Server and Microsoft Data Engine (MSDE) or approved equal.

2.2 DIRECT DIGITAL CONTROLLERS

A. Network Automation Engine (NAE 45XX)

1. The Network Automation Engine (NAE) shall be a fully user-programmable, supervisory controller. The NAE shall monitor the network of distributed application-specific controllers,

provide global strategy and direction, and communicate on a peer-to-peer basis with other Network Automation Engines.

2. Automation network - The NAE shall reside on the automation network and shall support a subnet of system controllers.
3. User Interface - Each NAE shall have the ability to deliver a web based User Interface (UI) as previously described. All computers connected physically or virtually to the automation network shall have access to the web based UI.
 - a. The web based UI software shall be imbedded in the NAE. Systems that require a local copy of the system database on the user's personal computer are not acceptable.
 - b. The NAE shall support a minimum of two (2) concurrent users.
 - c. The web based user shall have the capability to access all system data through one NAE.
 - d. Remote users connected to the network through an Internet Service Provider (ISP) or telephone dial up shall also have total system access through one NAE.
 - e. Systems that require the user to address more than one NAE to access all system information are not acceptable.
 - f. The NAE shall have the capability of generating web based UI graphics. The graphics capability shall be imbedded in the NAE.
 - g. Systems that support UI Graphics from a central database or require the graphics to reside on the user's personal computer are not acceptable.
 - h. The web based UI shall support the following functions using a standard version of Microsoft Internet Explorer:
 - ◇ Configuration
 - ◇ Commissioning
 - ◇ Data Archiving
 - ◇ Monitoring
 - ◇ Commanding
 - ◇ System Diagnostics
 - i. Systems that require workstation software or modified web browsers are not acceptable.
 - j. The NAE shall allow temporary use of portable devices without interrupting the normal operation of permanently connected modems.
4. Processor - The NAE shall be microprocessor-based with a minimum word size of 32 bits. The NAE shall be a multi-tasking, multi-user, and real-time digital control processor. Standard operating systems shall be employed. NAE size and capability shall be sufficient to fully meet the requirements of this Specification.
5. Memory - Each NAE shall have sufficient memory to support its own operating system, databases, and control programs, and to provide supervisory control for all control level devices.
6. Hardware Real Time Clock - The NAE shall include an integrated, hardware-Based, real-time clock.
7. The NAE shall include troubleshooting LED indicators to identify the following conditions:
 - a. Power - On/Off

- b. Ethernet Traffic - Ethernet Traffic/No Ethernet Traffic
 - c. Ethernet Connection Speed - 10 Mbps/100 Mbps
 - d. FC Bus - Normal Communications/No Field Communications
 - e. Peer Communication - Data Traffic between NAE Devices
 - f. Run - NAE Running/NAE in Startup/NAE Shutting Down/Software Not Running
 - g. Bat Fault - Battery Defective, Data Protection Battery Not Installed
 - h. Fault - General Fault
 - i. Modem RX - NAE Modem Receiving Data
 - j. Modem TX - NAE Modem Transmitting Data
8. Communications Ports - The NAE shall provide the following ports for operation of operator Input/Output (I/O) devices, such as industry-standard computers, modems, and portable operator's terminals.
- a. USB port
 - b. RS-232 serial data communication port
 - c. RS-485 port
 - d. Ethernet port
9. Diagnostics - The NAE shall continuously perform self-diagnostics, communication diagnosis, and diagnosis of all panel components. The Network Automation Engine shall provide both local and remote annunciation of any detected component failures, low battery conditions, or repeated failures to establish communication.
10. Power Failure - In the event of the loss of normal power, The NAE shall continue to operate for a user adjustable period of up to 10 minutes after which there shall be an orderly shutdown of all programs to prevent the loss of database or operating system software.
- a. During a loss of normal power, the control sequences shall go to the normal system shutdown conditions. All critical configuration data shall be saved into Flash memory.
 - b. Upon restoration of normal power and after a minimum off-time delay, the controller shall automatically resume full operation without manual intervention through a normal soft-start sequence.
11. Certification - The NAE shall be listed by Underwriters Laboratories (UL).
12. The NAE shall support a minimum of 100 control devices.

B. Field Equipment Controller (**FEC X610**)

- 1. The Field Equipment Controller (FEC) shall be a fully user-programmable, digital controller that communicates via BACnet MS/TP protocol.
 - a. The FEC shall support BACnet Standard MS/TP Bus Protocol ASHRAE SSPC-135, Clause 9 on the controller network.
 - ◊ The FEC shall be BACnet Testing Labs (BTL) certified and carry the BTL Label.
 - ◊ The FEC shall be tested and certified as a BACnet Application Specific Controller (B-ASC).

- ◇ A BACnet Protocol Implementation Conformance Statement shall be provided for the FEC.
 - ◇ The Conformance Statement shall be submitted 10 days prior to bidding.
2. The FEC shall employ a finite state control engine to eliminate unnecessary conflicts between control functions at crossover points in their operational sequences. Suppliers using non-state based DDC shall provide separate control strategy diagrams for all controlled functions in their submittals.
 3. Controllers shall be factory programmed with a continuous adaptive tuning algorithm that senses changes in the physical environment and continually adjusts loop tuning parameters appropriately. Controllers that require manual tuning of loops or perform automatic tuning on command only shall not be acceptable. The FEC shall be assembled in a plenum-rated plastic housing with flammability rated to UL94-5VB.

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 4. The FEC shall include troubleshooting LED indicators to identify the following conditions:
 - a. Power On
 - b. Power Off
 - c. Download or Startup in progress, not ready for normal operation
 - d. No Faults
 - e. Device Fault
 - f. Field Controller Bus - Normal Data Transmission
 - g. Field Controller Bus - No Data Transmission
 - h. Field Controller Bus - No Communication
 - i. Sensor-Actuator Bus - Normal Data Transmission
 - j. Sensor-Actuator Bus - No Data Transmission
 - k. Sensor-Actuator Bus - No Communication
 5. The FEC shall accommodate the direct wiring of analog and binary I/O field points.
 6. The FEC shall support the following types of inputs and outputs:
 - a. Universal Inputs - shall be configured to monitor any of the following:
 - ◇ Analog Input, Voltage Mode
 - ◇ Analog Input, Current Mode
 - ◇ Analog Input, Resistive Mode
 - ◇ Binary Input, Dry Contact Maintained Mode
 - ◇ Binary Input, Pulse Counter Mode
 - b. Binary Inputs - shall be configured to monitor either of the following:
 - ◇ Dry Contact Maintained Mode
 - ◇ Pulse Counter Mode
 - c. Analog Outputs - shall be configured to output either of the following
 - ◇ Analog Output, Voltage Mode
 - ◇ Analog Output, current Mode
 - d. Binary Outputs - shall output the following:

- ◇ 24 VAC Triac
- e. Configurable Outputs - shall be capable of the following:
 - ◇ Analog Output, Voltage Mode
 - ◇ Binary Output Mode
- 7. The FEC shall have the ability to reside on a Field Controller Bus (FC Bus).
 - a. The FC Bus shall be a Master-Slave/Token-Passing (MS/TP) Bus supporting BACnet Standard protocol SSPC-135, Clause 9.
 - b. The FC Bus shall support communications between the FECs and the NAE.
 - c. The FC Bus shall also support Input/Output Module (IOM) communications with the FEC and with the NAE.
 - d. The FC Bus shall support a minimum of 100 IOMs and FECs in any combination.
 - e. The FC Bus shall operate at a maximum distance of 15,000 Ft. between the FEC and the furthest connected device.
- 8. The FEC shall have the ability to monitor and control a network of sensors and actuators over a Sensor-Actuator Bus (SA Bus).
 - a. The SA Bus shall be a Master-Slave/Token-Passing (MS/TP) Bus supporting BACnet Standard Protocol SSPC-135, Clause 9.
 - b. The SA Bus shall support a minimum of 10 devices per trunk.
 - c. The SA Bus shall operate at a maximum distance of 1,200 Ft. between the FEC and the furthest connected device.
- 9. The FEC shall have the capability to execute complex control sequences involving direct wired I/O points as well as input and output devices communicating over the FC Bus or the SA Bus.
- 10. The FEC shall support a Local Controller Display (DIS1710) either as an integral part of the FEC or as a remote device communicating over the SA Bus.
 - a. The Display shall use a BACnet Standard SSPC-135, clause 9 Master-Slave/Token-Passing protocol.
 - b. The Display shall allow the user to view monitored points without logging into the system.
 - c. The Display shall allow the user to view and change setpoints, modes of operation, and parameters.
 - d. The Display shall provide password protection with user adjustable password timeout.
 - e. The Display shall be menu driven with separate paths for:
 - ◇ Input/Output
 - ◇ Parameter/Setpoint
 - ◇ Overrides
 - f. The Display shall use easy-to-read English text messages.
 - g. The Display shall allow the user to select the points to be shown and in what order.

- h. The Display shall support a back lit Liquid Crystal Display (LCD) with adjustable contrast and brightens and automatic backlight brightening during user interaction.
- i. The display shall be a minimum of 4 lines and a minimum of 20 characters per line
- j. The Display shall have a keypad with no more than 6 keys.
- k. The Display shall be panel mountable.

C. Input/Output Module (**IOM X710**)

- 1. The Input/Output Module (IOM) provides additional inputs and outputs for use in the FEC.
- 2. The IOM shall communicate with the FEC over the FC Bus or the SA Bus.
- 3. The IOM shall support BACnet Standard MS/TP Bus Protocol ASHRAE SSPC-135, Clause 9 on the controller network.
 - a. The IOM shall be BACnet Testing Labs (BTL) certified and carry the BTL Label.
 - b. The IOM shall be tested and certified as a BACnet Application Specific Controller (B-ASC).
 - c. A BACnet Protocol Implementation Conformance Statement shall be provided for the FEC.
 - d. The Conformance Statement shall be submitted 10 days prior to bidding.
- 4. The IOM shall be assembled in a plenum-rated plastic housing with flammability rated to UL94-5VB.
- 5. The IOM shall have a minimum of 4 points to a maximum of 17 points.
- 6. The IOM shall support the following types of inputs and outputs:
 - a. Universal Inputs - shall be configured to monitor any of the following:
 - ◇ Analog Input, Voltage Mode
 - ◇ Analog Input, Current Mode
 - ◇ Analog Input, Resistive Mode
 - ◇ Binary Input, Dry Contact Maintained Mode
 - ◇ Binary Input, Pulse Counter Mode
 - b. Binary Inputs - shall be configured to monitor either of the following:
 - ◇ Dry Contact Maintained Mode
 - ◇ Pulse Counter Mode
 - c. Analog Outputs - shall be configured to output either of the following
 - ◇ Analog Output, Voltage Mode
 - ◇ Analog Output, current Mode
 - d. Binary Outputs - shall output the following:
 - ◇ 24 VAC Triac
 - e. Configurable Outputs - shall be capable of the following:
 - ◇ Analog Output, Voltage Mode
 - ◇ Binary Output Mode

7. The IOM shall include troubleshooting LED indicators to identify the following conditions:
 - a. Power On
 - b. Power Off
 - c. Download or Startup in progress, not ready for normal operation
 - d. No Faults
 - e. Device Fault
 - f. Normal Data Transmission
 - g. No Data Transmission
 - h. No Communication

D. Networked Thermostat (**TEC 26X6**)

1. The networked thermostat shall be capable of controlling two- or four-pipe fan coils, cabinet unit heaters or other similar equipment.
2. The TEC shall communicate over the Field Controller Bus using BACnet Standard MS/TP Bus Protocol ASHRAE SSPC-135, Clause 9.
3. The TEC shall be BACnet Testing Labs (BTL) certified and carry the BTL Label.
 - a. The TEC shall be tested and certified as a BACnet Application Specific Controller (B-ASC).
 - b. A BACnet Protocol Implementation Conformance Statement shall be provided for the TEC.
 - c. The Conformance Statement shall be submitted 10 days prior to bidding.
4. The Networked Thermostat shall support remote read/write and parameter adjustment from the web based User Interfaceable through a Network Automation Engine.
5. The Networked Thermostat shall include an intuitive User Interface providing plain text messages.
 - a. Two line, 8 character backlit display
 - b. LED indicators for Fan, Heat, and Cool status
 - c. Five (5) User Interface Keys
 - ◇ Mode
 - ◇ Fan
 - ◇ Override
 - ◇ Degrees C/F
 - ◇ Up/Down
 - d. The display shall continuously scroll through the following parameters:
 - ◇ Room Temperature
 - ◇ System Mode
 - ◇ Schedule Status - Occupied/Unoccupied/Override
 - ◇ Applicable Alarms
6. The Networked Thermostat shall provide the flexibility to support any one of the following inputs:
 - a. Integral Indoor Air Temperature Sensor
 - b. Duct Mount Air Temperature Sensor
 - c. Remote Indoor Air Temperature Sensor with Occupancy Override and LED Indicator
 - d. Two configurable binary inputs

7. The Networked Thermostat shall provide the flexibility to support any one of the following outputs:
 - a. Three Speed Fan Control
 - b. Two On/Off
 - c. Two Floating
 - d. Two Proportional (0 to 10V)
8. The Networked Thermostat shall provide a minimum of six (6) levels of keypad lockout.
9. The Networked Thermostat shall provide the flexibility to adjust the following parameters:
 - a. Adjustable Temporary Occupancy from 0 to 24 hours
 - b. Adjustable heating/cooling deadband from 2° F to 5° F
 - c. Adjustable heating/cooling cycles per hour from 4 to 8
10. Where required by application and indicated on plans or room schedules provide the Networked Thermostat with an integral Passive Infra-Red (PIR) occupancy sensor.
11. The Networked Thermostat shall employ nonvolatile electrically erasable programmable read-only memory (EEPROM) for all adjustable parameters.

E. VAV Modular Assembly (VMA 16X0)

1. The VAV Modular Assembly shall provide both standalone and networked direct digital control of pressure-independent, variable air volume terminal units. It shall address both single and dual duct applications.
2. The VMA shall be BACnet Testing Labs (BTL) certified and carry the BTL Label.
 - a. The VMA shall be tested and certified as a BACnet Application Specific Controller (B-ASC).
 - b. A BACnet Protocol Implementation Conformance Statement shall be provided for the VMA.
 - c. The Conformance Statement shall be submitted 10 days prior to bidding.
3. The VAV Modular Assembly shall communicate over the FC Bus using BACnet Standard protocol SSPC-135, Clause 9.
4. The VAV Modular Assembly shall have internal electrical isolation for AC power, DC inputs, and MS/TP communications. An externally mounted isolation transformer shall not be acceptable.
5. The VAV Modular Assembly shall be a configurable digital controller with integral differential pressure transducer and damper actuator. All components shall be connected and mounted as a single assembly that can be removed as one piece.
6. The VAV Modular Assembly shall be assembled in a plenum-rated plastic housing with flammability rated to UL94-5VB.
7. The integral damper actuator shall be a fast response stepper motor capable of stroking 90 degrees in 30 seconds for quick damper positioning to speed commissioning and troubleshooting tasks.
8. The controller shall determine airflow by dynamic pressure measurement using an integral dead-ended differential

pressure transducer. The transducer shall be maintenance-free and shall not require air filters.

9. Each controller shall have the ability to automatically calibrate the flow sensor to eliminate pressure transducer offset error due to ambient temperature / humidity effects.
10. The controller shall utilize a proportional plus integration (PI) algorithm for the space temperature control loops.
11. Each controller shall continuously, adaptively tune the control algorithms to improve control and controller reliability through reduced actuator duty cycle. In addition, this tuning reduces commissioning costs, and eliminates the maintenance costs of manually re-tuning loops to compensate for seasonal or other load changes.
12. The controller shall provide the ability to download and upload VMA configuration files, both locally and via the communications network. Controllers shall be able to be loaded individually or as a group using a zone schedule generated spreadsheet of controller parameters.
13. Control setpoint changes initiated over the network shall be written to VMA non-volatile memory to prevent loss of setpoint changes and to provide consistent operation in the event of communication failure.
14. The controller firmware shall be flash-upgradeable remotely via the communications bus to minimize costs of feature enhancements.
15. The controller shall provide fail-soft operation if the airflow signal becomes unreliable, by automatically reverting to a pressure-dependent control mode.
16. The controller shall interface with balancer tools that allow automatic recalculation of box flow pickup gain ("K" factor), and the ability to directly command the airflow control loop to the box minimum and maximum airflow setpoints.
17. Controller performance shall be self-documenting via on-board diagnostics. These diagnostics shall consist of control loop performance measurements executing at each control loop's sample interval, which may be used to continuously monitor and document system performance. The VMA shall calculate exponentially weighted moving averages (EWMA) for each of the following. These metrics shall be available to the end user for efficient management of the VAV terminals.
 - ◇ Absolute temperature loop error
 - ◇ Signed temperature loop error
 - ◇ Absolute airflow loop error
 - ◇ Signed airflow loop error
 - ◇ Average damper actuator duty cycle
18. The controller shall detect system error conditions to assist in managing the VAV zones. The error conditions shall consist of:
 - ◇ Unreliable space temperature sensor
 - ◇ Unreliable differential pressure sensor
 - ◇ Starved box
 - ◇ Actuator stall

- ◇ Insufficient cooling
 - ◇ Insufficient heating

The controller shall provide a flow test function to view damper position vs. flow in a graphical format. The information would alert the user to check damper position. The VMA would also provide a method to calculate actuator duty cycle as an indicator of damper actuator runtime.
- 19. The controller shall provide a compliant interface for ASHRAE Standard 62-1989 (indoor air quality), and shall be capable of resetting the box minimum airflow Based on the percent of outdoor air in the primary air stream.
- 20. The controller shall comply with ASHRAE Standard 90.1 (energy efficiency) by preventing simultaneous heating and cooling, and where the control strategy requires reset of airflow while in reheat, by modulating the box reheat device fully open prior to increasing the airflow in the heating sequence.
- 21. Inputs:
 - a. Analog inputs with user defined ranges shall monitor the following analog signals, without the addition of equipment outside the terminal controller cabinet:
 - ◇ 0-10 VDC Sensors
 - ◇ 1000ohm RTDs
 - ◇ NTC Thermistors
 - b. Binary inputs shall monitor dry contact closures. Input shall provide filtering to eliminate false signals resulting from input "bouncing."
 - c. For noise immunity, the inputs shall be internally isolated from power, communications, and output circuits.
 - d. Provide side loop application for humidity control.
- 22. Outputs
 - a. Analog outputs shall provide the following control outputs:
 - ◇ 0-10 VDC
 - b. Binary outputs shall provide a SPST Triac output rated for 500mA at 24 VAC.
 - c. For noise immunity, the outputs shall be internally isolated from power, communications, and other output circuits.
- 23. Application Configuration
 - a. The VAV Modular Assembly shall be configured with a software tool that provides a simple Question/Answer format for developing applications and downloading.
- 24. Sensor Support
 - a. The VAV Modular Assembly shall communicate over the Sensor-Actuator Bus (SA Bus) with a Network Sensor.
 - b. The VMA shall support an LCD display room sensor.
 - c. The VMA shall also support standard room sensors as defined by analog input requirements.
 - d. The VMA shall support humidity sensors defined by the AI side loop.

F. Network Sensors (NS-XXX-700X)

1. The Network Sensors (NS) shall have the ability to monitor the following variables as required by the systems sequence of operations:
 - a. Zone Temperature
 - b. Zone Humidity
 - c. Zone Setpoint
 - d. Discharge Air Temperature
 - e. Zone CO2
2. The NS shall transmit the information back to the controller on the Sensor-Actuator Bus (SA Bus) using BACnet Standard protocol SSPC-135, Clause 9.
3. The NS shall be BACnet Testing Labs (BTL) certified and carry the BTL Label.
 - a. The NS shall be tested and certified as a BACnet Smart Sensors (B-SS).
 - b. A BACnet Protocol Implementation Conformance Statement shall be provided for the NS.
 - c. The Conformance Statement shall be submitted 10 days prior to bidding.
4. The Network Zone Temperature Sensors shall include the following items:
 - a. A backlit Liquid Crystal Display (LCD) to indicate the Temperature, Humidity and Setpoint
 - b. An LED to indicate the status of the Override feature
 - c. A button to toggle the temperature display between Fahrenheit and Celsius
 - d. A button to initiate a timed override command
 - e. Available in either surface mount or wall mount
 - f. Available with either screw terminals or phone jack
5. The Network Discharge Air Sensors shall include the following:
 - a. 4 inch or 8 inch duct insertion probe
 - b. 10 foot pigtail lead
 - c. Dip Switches for programmable address selection
 - d. Ability to provide an averaging temperature from multiple locations
 - e. Ability to provide a selectable temperature from multiple locations
6. The Network CO2 Zone Sensors shall include the following:
 - a. Available in either surface mount or wall mount
 - b. Available with screw terminals or phone jack

2.6 ENGINEERING CONTROL CENTER (ECC)—OPERATOR'S WORKSTATION

A. Existing Workstation. Provided Graphics on the Existing Johnson controls Extended Architecture Workstation.

B. Portable Operator Terminal

For systems that do not provide full access to systems configuration and definition via the Browser Based user interface the BMS Contractor shall provide a portable operator terminal for programming purposes. The terminal shall be configured as follows:

Personal Laptop Computer Manufacturer - Dell, Compaq or HP

1 GB RAM (256 MB minimum) - XP Professional

1.8 GHz Clock Speed Pentium 4 Microprocessor (800 MHz minimum)
 40 GB Hard Drive (40 GB minimum)
 (1) CD-ROM Drive, 32x speed
 (1) Serial (1) Parallel (2) USB ports
 1 Keyboard with 83 keys (minimum).
 Integral 2 button Track Point or Track Ball.
 10" SVGA 1024x768 resolution color display
 Two PCMCIA Type II or one Type III card slot
 Complete operator workstation software package, including any hardware or software.
 Original printed manuals for all software and peripherals.
 Original installation disks or CD for all software, device drivers, and peripherals
 Software registration cards for all included software shall be provided to the Owner.
 Carrying case
 Spare battery.
 External power supply/battery charger
 Software
 Portable operator terminals shall support all controllers within the system on a direct-connect communications basis.
 When used to access First or Second Tier controllers, the portable operator terminal shall utilize the standard operator workstation software, as previously defined.
 When used to access Application Specific Controllers, the portable operator terminal shall utilize either the standard operator workstation software, as previously defined, or controller-specific utility software.

2.7 CONTROL CABLES

As specified in Division 26.

1.8 Input Devices

A. General Requirements

1. Installation, testing, and calibration of all sensors, transmitters, and other input devices shall be provided to meet the system requirements.

B. Temperature Sensors

1. General Requirements:

- a. Sensors and transmitters shall be provided, as outlined in the input/output summary and sequence of operations.
- b. The temperature sensor shall be of the resistance type, and shall be either two-wire 1000 ohm nickel RTD, or two-wire 1000 ohm platinum RTD.
- c. The following point types (and the accuracy of each) are required, and their associated accuracy values include errors associated with the sensor, lead wire, and A to D conversion:

Point Type	Accuracy
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Point Type	Accuracy
Chilled Water	$\pm .5^{\circ}\text{F.}$
Room Temp	$\pm .5^{\circ}\text{F.}$
Duct Temperature	$\pm .5^{\circ}\text{F.}$
All Others	$\pm .75^{\circ}\text{F.}$

2. Room Temperature Sensors
 - a. Room sensors shall be constructed for either surface or wall box mounting.
 - b. Room sensors shall have the following options when specified:
 - ◇ Setpoint reset slide switch providing a ± 3 degree (adjustable) range.
 - ◇ Individual heating/cooling setpoint slide switches.
 - ◇ A momentary override request push button for activation of after-hours operation.
 - ◇ Analog thermometer.
3. Room Temperature Sensors with Integral Display
 - a. Room sensors shall be constructed for either surface or wall box mounting.
 - b. Room sensors shall have an integral LCD display and four button keypad with the following capabilities:
 - ◇ Display room and outside air temperatures.
 - ◇ Display and adjust room comfort setpoint.
 - ◇ Display and adjust fan operation status.
 - ◇ Timed override request push button with LED status for activation of after-hours operation.
 - ◇ Display controller mode.
 - ◇ Password selectable adjustment of setpoint and override modes.
4. Thermo wells
 - a. When thermo wells are required, the sensor and well shall be supplied as a complete assembly, including wellhead and Greenfield fitting.
 - b. Thermo wells shall be pressure rated and constructed in accordance with the system working pressure.
 - c. Thermo wells and sensors shall be mounted in a threadolet or 1/2" NFT saddle and allow easy access to the sensor for repair or replacement.
 - d. Thermo wells shall be constructed of 316 stainless steel.
5. Outside Air Sensors
 - a. Outside air sensors shall be designed to withstand the environmental conditions to which they will be exposed. They shall also be provided with a solar shield.
 - b. Sensors exposed to wind velocity pressures shall be shielded by a perforated plate that surrounds the sensor element.
 - c. Temperature transmitters shall be of NEMA 3R construction and rated for ambient temperatures.

6. Duct Mount Sensors

- a. Duct mount sensors shall mount in an electrical box through a hole in the duct, and be positioned so as to be easily accessible for repair or replacement.
- b. Duct sensors shall be insertion type and constructed as a complete assembly, including lock nut and mounting plate.
- c. For outdoor air duct applications, a weatherproof mounting box with weatherproof cover and gasket shall be used.

7. Averaging Sensors

- a. For ductwork greater in any dimension than 48 inches and/or where air temperature stratification exists, an averaging sensor with multiple sensing points shall be used.
- b. For plenum applications, such as mixed air temperature measurements, a string of sensors mounted across the plenum shall be used to account for stratification and/or air turbulence. The averaging string shall have a minimum of 4 sensing points per 12-foot long segment.
- c. Capillary supports at the sides of the duct shall be provided to support the sensing string.

8. Acceptable Manufacturers: Johnson Controls, Setra.

C. Humidity Sensors

1. The sensor shall be a solid-state type, relative humidity sensor of the Bulk Polymer Design. The sensor element shall resist service contamination.
2. The humidity transmitter shall be equipped with non-interactive span and zero adjustments, a 2-wire isolated loop powered, 4-20 mA, 0-100% linear proportional output.
3. The humidity transmitter shall meet the following overall accuracy, including lead loss and Analog to Digital conversion. 3% between 20% and 80% RH @ 77 Deg F unless specified elsewhere.
4. Outside air relative humidity sensors shall be installed with a rain proof, perforated cover. The transmitter shall be installed in a NEMA 3R enclosure with sealtite fittings and stainless steel bushings.
5. A single point humidity calibrator shall be provided, if required, for field calibration. Transmitters shall be shipped factory pre-calibrated.
6. Duct type sensing probes shall be constructed of 304 stainless steel, and shall be equipped with a neoprene grommet, bushings, and a mounting bracket.
7. Acceptable Manufacturers: Johnson Controls, Veris Industries, and Mamac.

D. Differential Pressure Transmitters

1. General Air and Water Pressure Transmitter Requirements:
 - a. Pressure transmitters shall be constructed to withstand 100% pressure over-range without damage, and to hold calibrated accuracy when subject to a momentary 40% over-range input.

- b. Pressure transmitters shall transmit a 0 to 5 VDC, 0 to 10 VDC, or 4 to 20 mA output signal.
 - c. Differential pressure transmitters used for flow measurement shall be sized to the flow sensing device, and shall be supplied with Tee fittings and shut-off valves in the high and low sensing pick-up lines to allow the balancing Contractor and Owner permanent, easy-to-use connection.
 - d. A minimum of a NEMA 1 housing shall be provided for the transmitter. Transmitters shall be located in accessible local control panels wherever possible.
- 2. Low Differential Water Pressure Applications (0" - 20" w.c.)
 - a. The differential pressure transmitter shall be of industrial quality and transmit a linear, 4 to 20 mA output in response to variation of flow meter differential pressure or water pressure sensing points.
 - b. The differential pressure transmitter shall have non-interactive zero and span adjustments that are adjustable from the outside cover and meet the following performance specifications:
 - ◇ .01-20" w.c. input differential pressure range.
 - ◇ 4-20 mA output.
 - ◇ Maintain accuracy up to 20 to 1 ratio turndown.
 - ◇ Reference Accuracy: +0.2% of full span.
 - c. Acceptable Manufacturers: Setra and Mamac.
- 3. Medium to High Differential Water Pressure Applications (Over 21" w.c.)
 - a. The differential pressure transmitter shall meet the low pressure transmitter specifications with the following exceptions:
 - ◇ Differential pressure range 10" w.c. to 300 PSI.
 - ◇ Reference Accuracy: +1% of full span (includes non-linearity, hysteresis, and repeatability).
 - b. Standalone pressure transmitters shall be mounted in a bypass valve assembly panel. The panel shall be constructed to NEMA 1 standards. The transmitter shall be installed in the panel with high and low connections piped and valved. Air bleed units, bypass valves, and compression fittings shall be provided.
 - c. Acceptable Manufacturers: Setra and Mamac.
- 4. Building Differential Air Pressure Applications (-1" to +1" w.c.)
 - a. The differential pressure transmitter shall be of industrial quality and transmit a linear, 4 to 20 mA output in response to variation of differential pressure or air pressure sensing points.
 - b. The differential pressure transmitter shall have non-interactive zero and span adjustments that are adjustable from the outside cover and meet the following performance specifications:
 - ◇ -1.00 to +1.00 w.c. input differential pressure ranges. (Select range appropriate for system application)

- ◇ 4-20 mA output.
 - ◇ Maintain accuracy up to 20 to 1 ratio turndown.
 - ◇ Reference Accuracy: +0.2% of full span.
- c. Acceptable Manufacturers: Johnson Controls and Setra.
- 5. Low Differential Air Pressure Applications (0" to 5" w.c.)
 - a. The differential pressure transmitter shall be of industrial quality and transmit a linear, 4 to 20 mA output in response to variation of differential pressure or air pressure sensing points.
 - b. The differential pressure transmitter shall have non-interactive zero and span adjustments that are adjustable from the outside cover and meet the following performance specifications:
 - ◇ (0.00 - 1.00" to 5.00") w.c. input differential pressure ranges. (Select range appropriate for system application.)
 - ◇ 4-20 mA output.
 - ◇ Maintain accuracy up to 20 to 1 ratio turndown.
 - ◇ Reference Accuracy: +0.2% of full span.
 - c. Acceptable Manufacturers: Johnson Controls and Setra.
- 6. Medium Differential Air Pressure Applications (5" to 21" w.c.)
 - a. The pressure transmitter shall be similar to the Low Air Pressure Transmitter, except that the performance specifications are not as severe. Differential pressure transmitters shall be provided that meet the following performance requirements:
 - ◇ Zero & span: (c/o F.S./Deg. F): .04% including linearity, hysteresis and repeatability.
 - ◇ Accuracy: 1% F.S. (best straight line) Static Pressure Effect: 0.5% F.S. (to 100 PSIG.
 - ◇ Thermal Effects: <+.033 F.S./Deg. F. over 40°F. to 100°F. (calibrated at 70°F.).
 - b. Standalone pressure transmitters shall be mounted in a bypass valve assembly panel. The panel shall be constructed to NEMA 1 standards. The transmitter shall be installed in the panel with high and low connections piped and valved. Air bleed units, bypass valves, and compression fittings shall be provided.
 - c. Acceptable manufacturers: Johnson Controls and Setra.

E. Flow Monitoring

- 1. Air Flow Monitoring
 - a. Fan Inlet Air Flow Measuring Stations
 - ◇ At the inlet of each fan and near the exit of the inlet sound trap, airflow traverse probes shall be provided that shall continuously monitor the fan air volumes and system velocity pressure.
 - ◇ Each traverse probe shall be of a dual manifolded, cylindrical, type 3003 extruded aluminum configuration, having an anodized finish to eliminate surface pitting and unnecessary air friction. The multiple total pressure manifold shall have sensors located along the stagnation

plane of the approaching airflow. The manifold should not have forward projecting sensors into the air stream. The static pressure manifold shall incorporate dual offset static tops on the opposing sides of the averaging manifold so as to be insensitive to flow-angle variations of as much as $\pm 20^\circ$ in the approaching air stream.

- ◇ The airflow traverse probe shall not induce a measurable pressure drop, nor shall the sound level within the duct be amplified by its singular or multiple presence in the air stream. Each airflow-measuring probe shall contain multiple total and static pressure sensors placed at equal distances along the probe length. The number of sensors on each probe and the quantity of probes utilized at each installation shall comply with the ASHRAE Standards for duct traversing.
- ◇ Airflow measuring stations shall be manufactured by Air Monitor Corp., Tek-Air Systems, Inc., Ebtron, or Dietrich Standard.

b. Single Probe Air Flow Measuring Sensor

- ◇ The single probe airflow-measuring sensor shall be duct mounted with an adjustable sensor insertion length of up to eight inches. The transmitter shall produce a 4-20 mA or 0-10 VDC signal linear to air velocity. The sensor shall be a hot wire anemometer and utilize two temperature sensors and a heater element temperature. The other sensor shall measure the downstream air temperature. The temperature differential shall be directly related to airflow velocity.

c. Duct Air Flow Measuring Stations

- ◇ Each device shall be designed and built to comply with, and provide results in accordance with, accepted practice as defined for system testing in the ASHRAE Handbook of fundamentals, as well as in the Industrial Ventilation Handbook.
- ◇ Airflow measuring stations shall be fabricated of 14-gauge galvanized steel welded casing with 90 Deg. connecting flanges in configuration and size equal to that of the duct into which it is mounted. Each station shall be complete with an air directionalizer and parallel cell profile suppressor (3/4" maximum cell) across the entering air stream and mechanically fastened to the casing in such a way to withstand velocities up to 6000 feet per minute. This air directionalizer and parallel cell honeycomb suppressor shall provide 98% free area, equalize the velocity profile, and eliminate turbulent and rotational flow from the air stream prior to the measuring point.
- ◇ The total pressure measurement side (high side) will be designed and spaced to the Industrial Ventilation Manual 16th Edition, Page 9-5. The

self-averaging manifolding will be manufactured of brass and copper components.

- ◇ The static pressure sensing probes (low side) shall be bullet-nosed shaped, per detailed radius, as illustrated in Industrial Ventilation Manual 16th Edition, Page 9-5.
- ◇ The main take-off point from both the total pressure and the static pressure manifolds must be symmetrical.
- ◇ Total and static pressure manifolds shall terminate with external ports for connection to control tubing. An identification label shall be placed on each unit casing, listing model number, size, area, and specified airflow capacity.
- ◇ Installation Considerations

(i) *The maximum allowable pressure loss through the Flow and Static Pressure elements shall not exceed .065" w.c. at 1000 feet per minute, or .23" w.c. at 2000 feet per minute. Each unit shall measure the airflow rate within an accuracy of plus 2% as determined by U.S. - GSA certification tests, and shall contain a minimum of one total pressure sensor per 36 square inches of unit measuring area.*

(ii) *The units shall have a self-generated sound rating of less than NC40, and the sound level within the duct shall not be amplified nor shall additional sound be generated.*

(iii) *Where the stations are installed in insulated ducts, the airflow passage of the station shall be the same size as the inside airflow dimension of the duct. Station flanges shall be two inch to three inch to facilitate matching connecting ductwork.*

(iv) *Where control dampers are shown as part of the airflow measuring station, opposed blade precision controlled volume dampers integral to the station and complete with actuator, pilot positioner, and linkage shall be provided.*

(v) *Stations shall be installed in strict accordance with the manufacturer's published requirements, and in accordance with ASME Guidelines affecting non-standard approach conditions.*

- ◇ Acceptable manufacturers: Air Monitor Corp., Tek-Air, Ebtron, and Dietrich Standard.
- d. Static Pressure Traverse Probe
 - ◇ Duct static traverse probes shall be provided where required to monitor duct static pressure. The probe shall contain multiple static pressure sensors located along exterior surface of the cylindrical probe.
 - ◇ Acceptable manufacturers: Cleveland Controls
- e. Shielded Static Air Probe
 - ◇ A shielded static pressure probe shall be provided at each end of the building. The probe shall have multiple sensing ports, an impulse suppression chamber, and airflow shielding. A suitable probe for indoor and outdoor locations shall be provided.
- 2. Water Flow Monitoring
 - ◇ Water flow meters shall be electromagnetic type with integral microprocessor-Based electronics. The meter shall have an accuracy of 0.25%.
 - ◇ Acceptable manufacturers: Onicon

F. Status and Safety Switches

- 1. General Requirements
 - a. Switches shall be provided to monitor equipment status, safety conditions, and generate alarms at the BMS when a failure or abnormal condition occurs. Safety switches shall be provided with two sets of contacts and shall be interlock wired to shut down respective equipment.
- 2. Current Sensing Switches
 - a. The current sensing switch shall be self-powered with solid-state circuitry and a dry contact output. It shall consist of a current transformer, a solid state current sensing circuit, adjustable trip point, solid state switch, SPDT relay, and an LED indicating the on or off status. A conductor of the load shall be passed through the window of the device. It shall accept over-current up to twice its trip point range.
 - b. Current sensing switches shall be used for run status for fans, pumps, and other miscellaneous motor loads.
 - c. Current sensing switches shall be calibrated to show a positive run status only when the motor is operating under load. A motor running with a broken belt or coupling shall indicate a negative run status.
 - d. Acceptable manufacturers: Veris Industries
- 3. Air Filter Status Switches
 - a. Differential pressure switches used to monitor air filter status shall be of the automatic reset type with SPDT contacts rated for 2 amps at 120VAC.
 - b. A complete installation kit shall be provided, including: static pressure taps, tubing, fittings, and air filters.

- c. Provide appropriate scale range and differential adjustment for intended service.
 - d. Acceptable manufacturers: Johnson Controls, Cleveland Controls
- 4. Air Flow Switches
 - a. Differential pressure flow switches shall be bellows actuated mercury switches or snap acting micro-switches with appropriate scale range and differential adjustment for intended service.
 - b. Acceptable manufacturers: Johnson Controls, Cleveland Controls
- 5. Air Pressure Safety Switches
 - a. Air pressure safety switches shall be of the manual reset type with SPDT contacts rated for 2 amps at 120VAC.
 - b. Pressure range shall be adjustable with appropriate scale range and differential adjustment for intended service.
 - c. Acceptable manufacturers: Johnson Controls, Cleveland Controls
- 6. Water Flow Switches
 - a. Water flow switches shall be equal to the Johnson Controls P74.
- 7. Low Temperature Limit Switches
 - a. The low temperature limit switch shall be of the manual reset type with Double Pole/Single Throw snap acting contacts rated for 16 amps at 120VAC.
 - b. The sensing element shall be a minimum of 15 feet in length and shall react to the coldest 18-inch section. Element shall be mounted horizontally across duct in accordance with manufacturers recommended installation procedures.
 - c. For large duct areas where the sensing element does not provide full coverage of the air stream, additional switches shall be provided as required to provide full protection of the air stream.
 - d. The low temperature limit switch shall be equal to Johnson Controls A70.

2.9 Output Devices

A Actuators

- 8. General Requirements
 - a. Damper and valve actuators shall be electronic and/or pneumatic, as specified in the System Description section.
- 9. Electronic Damper Actuators
 - a. Electronic damper actuators shall be direct shaft mount.
 - b. Modulating and two-position actuators shall be provided as required by the sequence of operations. Damper sections shall be sized Based on actuator manufacturer's recommendations for face velocity, differential pressure

and damper type. The actuator mounting arrangement and spring return feature shall permit normally open or normally closed positions of the dampers, as required. All actuators (except terminal units) shall be furnished with mechanical spring return unless otherwise specified in the sequences of operations. All actuators shall have external adjustable stops to limit the travel in either direction, and a gear release to allow manual positioning.

- c. Modulating actuators shall accept 24 VAC or VDC power supply, consume no more than 15 VA, and be UL listed. The control signal shall be 2-10 VDC or 4-20 mA, and the actuator shall provide a clamp position feedback signal of 2-10 VDC. The feedback signal shall be independent of the input signal and may be used to parallel other actuators and provide true position indication. The feedback signal of one damper actuator for each separately controlled damper shall be wired back to a terminal strip in the control panel for trouble-shooting purposes.
- d. Two-position or open/closed actuators shall accept 24 or 120 VAC power supply and be UL listed. Isolation, smoke, exhaust fan, and other dampers, as specified in the sequence of operations, shall be furnished with adjustable end switches to indicate open/closed position or be hard wired to start/stop associated fan. Two-position actuators, as specified in sequences of operations as "quick acting," shall move full stroke within 20 seconds. All smoke damper actuators shall be quick acting.
- e. Acceptable manufacturers: Johnson Controls, Mamac.

10. Electronic Valve Actuators

- a. Electronic valve actuators shall be manufactured by the valve manufacturer.
- b. Each actuator shall have current limiting circuitry incorporated in its design to prevent damage to the actuator.
- c. Modulating and two-position actuators shall be provided as required by the sequence of operations. Actuators shall provide the minimum torque required for proper valve close-off against the system pressure for the required application. The valve actuator shall be sized Based on valve manufacturer's recommendations for flow and pressure differential. All actuators shall fail in the last position unless specified with mechanical spring return in the sequence of operations. The spring return feature shall permit normally open or normally closed positions of the valves, as required. All direct shaft mount rotational actuators shall have external adjustable stops to limit the travel in either direction.
- d. Modulating Actuators shall accept 24 VAC or VDC and 120 VAC power supply and be UL listed. The control signal shall be 2-10 VDC or 4-20 mA and the actuator shall provide a clamp position feedback signal of 2-10 VDC. The feedback signal shall be independent of the input

signal, and may be used to parallel other actuators and provide true position indication. The feedback signal of each valve actuator (except terminal valves) shall be wired back to a terminal strip in the control panel for trouble-shooting purposes.

- e. Two-position or open/closed actuators shall accept 24 or 120 VAC power supply and be UL listed. Butterfly isolation and other valves, as specified in the sequence of operations, shall be furnished with adjustable end switches to indicate open/closed position or be hard wired to start/stop the associated pump or chiller.
- f. Acceptable manufacturers: Johnson Controls

B Control Dampers

- 11. The BMS Contractor shall furnish all automatic dampers. All automatic dampers shall be sized for the application by the BMS Contractor or as specifically indicated on the Drawings.
- 12. All dampers used for throttling airflow shall be of the opposed blade type arranged for normally open or normally closed operation, as required. The damper is to be sized so that, when wide open, the pressure drop is a sufficient amount of its close-off pressure drop to shift the characteristic curve to near linear.
- 13. All dampers used for two-position, open/close control shall be parallel blade type arranged for normally open or closed operation, as required.
- 14. Damper frames and blades shall be constructed of either galvanized steel or aluminum. Maximum blade length in any section shall be 60". Damper blades shall be 16-gauge minimum and shall not exceed eight (8) inches in width. Damper frames shall be 16-gauge minimum hat channel type with corner bracing. All damper bearings shall be made of reinforced nylon, stainless steel or oil-impregnated bronze. Dampers shall be tight closing, low leakage type, with synthetic elastomer seals on the blade edges and flexible stainless steel side seals. Dampers of 48"x48" size shall not leak in excess of 8.0 cfm per square foot when closed against 4" w.g. static pressure when tested in accordance with AMCA Std. 500.
- 15. Airfoil blade dampers of double skin construction with linkage out of the air stream shall be used whenever the damper face velocity exceeds 1500 FPM or system pressure exceeds 2.5" w.g., but no more than 4000 FPM or 6" w.g. Acceptable manufacturers are Johnson Controls D-7250 D-1250 or D-1300, Ruskin CD50, and Vent Products 5650.
- 16. One piece rolled blade dampers with exposed or concealed linkage may be used with face velocities of 1500 FPM or below. Acceptable manufacturers are: Johnson Controls D-1600, Ruskin CD36, and Vent Products 5800.
- 17. Multiple section dampers may be jack-shafted to allow mounting of piston pneumatic actuators and direct connect electronic actuators. Each end of the jackshaft shall receive at least one actuator to reduce jackshaft twist.

G. Control Relays

- 1. Control Pilot Relays

- a. Control pilot relays shall be of a modular plug-in design with retaining springs or clips.
- b. Mounting Bases shall be snap-mount.
- c. DPDT, 3PDT, or 4PDT relays shall be provided, as appropriate for application.
- d. Contacts shall be rated for 10 amps at 120VAC.
- e. Relays shall have an integral indicator light and check button.
- f. Acceptable manufacturers: Johnson Controls, Lectro

H. Control Valves

1. All automatic control valves shall be fully proportioning and provide near linear heat transfer control. The valves shall be quiet in operation and fail-safe open, closed, or in their last position. All valves shall operate in sequence with another valve when required by the sequence of operations. All control valves shall be sized by the control manufacturer, and shall be guaranteed to meet the heating and cooling loads, as specified. All control valves shall be suitable for the system flow conditions and close against the differential pressures involved. Body pressure rating and connection type (sweat, screwed, or flanged) shall conform to the pipe schedule elsewhere in this Specification.
2. Chilled water control valves shall be modulating plug, ball, and/or butterfly, as required by the specific application. Modulating water valves shall be sized per manufacturer's recommendations for the given application. In general, valves (2 or 3-way) serving **variable** flow air handling unit coils shall be sized for a pressure drop equal to the actual coil pressure drop, but no less than 5 PSI. Valves (3-way) serving **constant** flow air handling unit coils with secondary circuit pumps shall be sized for a pressure drop equal to 25% the actual coil pressure drop, but no less than 2 PSI. Mixing valves (3-way) serving secondary water circuits shall be sized for a pressure drop of no less than 5 PSI. Valves for terminal reheat coils shall be sized for a 2 PSIG pressure drop, but no more than a 5 PSI drop.
3. Ball valves shall be used for hot and chilled water applications, water terminal reheat coils, radiant panels, unit heaters, package air conditioning units, and fan coil units except those described hereinafter.
4. Modulating plug water valves of the single-seat type with equal percentage flow characteristics shall be used for all special applications as indicated on the valve schedule. Valve discs shall be composition type. Valve stems shall be stainless steel.
5. Butterfly valves shall be acceptable for modulating large flow applications greater than modulating plug valves, and for all two-position, open/close applications. In-line and/or three-way butterfly valves shall be heavy-duty pattern with a body rating comparable to the pipe rating, replaceable lining suitable for temperature of system, and a stainless steel vane. Valves for modulating service shall be sized and travel limited to 50 degrees of full open. Valves for isolation

service shall be the same as the pipe. Valves in the closed position shall be bubble-tight.

6. Acceptable manufacturers: Johnson Controls

I. Electronic Signal Isolation Transducers

1. A signal isolation transducer shall be provided whenever an analog output signal from the BMS is to be connected to an external control system as an input (such as a chiller control panel), or is to receive as an input signal from a remote system.
2. The signal isolation transducer shall provide ground plane isolation between systems.
3. Signals shall provide optical isolation between systems.
4. Acceptable manufacturers: Advanced Control Technologies

J. External Manual Override Stations

1. External manual override stations shall provide the following:
 - a. An integral HAND/OFF/AUTO switch shall override the controlled device pilot relay.
 - b. A status input to the Facility Management System shall indicate whenever the switch is not in the automatic position.
 - c. A Status LED shall illuminate whenever the output is ON.
 - d. An Override LED shall illuminate whenever the HOA switch is in either the HAND or OFF position.
 - e. Contacts shall be rated for a minimum of 1 amp at 24 VAC.

3.0 Miscellaneous Devices

A Local Control Panels

1. All control panels shall be factory constructed, incorporating the BMS manufacturer's standard designs and layouts. All control panels shall be UL inspected and listed as an assembly and carry a UL 508 label listing compliance. Control panels shall be fully enclosed, with perforated sub-panel, hinged door, and slotted flush latch.
2. In general, the control panels shall consist of the DDC controller(s), display module as specified and indicated on the plans, and I/O devices—such as relays, transducers, and so forth—that are not required to be located external to the control panel due to function. Where specified the display module shall be flush mounted in the panel face unless otherwise noted.
3. All I/O connections on the DDC controller shall be provide via removable or fixed screw terminals.
4. Low and line voltage wiring shall be segregated. All provided terminal strips and wiring shall be UL listed, 300-volt service and provide adequate clearance for field wiring.

5. All wiring shall be neatly installed in plastic trays or tie-wrapped.
6. A convenience 120 VAC duplex receptacle shall be provided in each enclosure, fused on/off power switch, and required transformers.

K. Power Supplies

1. DC power supplies shall be sized for the connected device load. Total rated load shall not exceed 75% of the rated capacity of the power supply.
2. Input: 120 VAC +10%, 60Hz.
3. Output: 24 VDC.
4. Line Regulation: +0.05% for 10% line change.
5. Load Regulation: +0.05% for 50% load change.
6. Ripple and Noise: 1 mV rms, 5 mV peak to peak.
7. An appropriately sized fuse and fuse block shall be provided and located next to the power supply.
8. A power disconnect switch shall be provided next to the power supply.

L. Thermostats

1. Electric room thermostats of the heavy-duty type shall be provided for unit heaters, cabinet unit heaters, and ventilation fans, where required. All these items shall be provided with concealed adjustment. Finish of covers for all room-type instruments shall match and, unless otherwise indicated or specified, covers shall be manufacturer's standard finish.

PART 4 - EXECUTION

4.1 INSTALLATION

A. General:

1. Examine project plans for control devices and equipment locations; and report any discrepancies, conflicts, or omissions to Resident Engineer for resolution before proceeding for installation.
2. Work Coordination: Section 00 72 00, GENERAL CONDITIONS.
3. Install equipment, piping, wiring /conduit parallel to or at right angles to building lines.
4. Install all equipment and piping in readily accessible locations. Do not run tubing and conduit concealed under insulation or inside ducts.
5. Mount control devices, tubing and conduit located on ducts and apparatus with external insulation on standoff support to avoid interference with insulation.
6. Provide sufficient slack and flexible connections to allow for vibration of piping and equipment.
7. Run wire connecting devices on or in control cabinets parallel with the sides of the cabinet neatly racked to permit tracing.
8. Install equipment level and plum.

B. Piping Installation:

1. All piping associated with smoke control shall be hard drawn copper.
2. Tubing passing through or buried in concrete shall be installed in

rigid steel conduit of sufficient strength to prevent damage to tubing.

3. Except for short apparatus connections, non-metallic tubing in all exposed locations, including mechanical rooms shall be protected from damage by installing the tubing in electric conduit or raceways. Provide protective grommet where tubing exits conduit.

4. Non-metallic tubing exposed to outdoors shall be protected by a sleeve or larger tubing.

5. In concealed but accessible locations such as above lay-in ceilings, non-metallic tubing may be run without conduit or raceway.

6. All tubing which is not run in conduit or raceway, both metallic and non-metallic, shall be neatly routed and securely fastened to building structure at not more than 36-IN. intervals.

7. Welding shall be performed in accordance with Section 23 21 13, HYDRONIC PIPING and Section 23 22 13, STEAM AND CONDENSATE HEATING PIPING.

8. Label and identify control air piping in accordance with specification Section 23 05 11, COMMON WORK RESULTS FOR HVAC AND STEAM GENERATION.

C. Electrical Wiring Installation:

1. Install conduits and wiring in accordance with Specification Section 26 05 33, RACEWAY AND BOXES FOR ELECTRICAL SYSTEMS.

2. Install signal and communication cables in accordance with the control manufacturer's requirements with regard to wiring sizing, type, number of conductors, shielding, to ensure proper operation of the system.

3. Install conduit and wiring between operator workstation(s), digital controllers, electrical panels, indicating devices, instrumentation, miscellaneous alarm points, thermostats, and relays as shown on the drawings or as required under this section. All wiring shall be installed in conduits.

4. Install all electrical work required for a fully functional system and not shown on electrical plans or required by electrical specifications. Where low voltage power is required, provide suitable transformers.

5. Install all system components in accordance with local Building Code and National Electric Code.

a. Splices: Splices in shielded and coaxial cables shall consist of terminations and the use of shielded cable couplers. Terminations shall be in accessible locations. Cables shall be harnessed with cable ties.

b. Equipment: Fit all equipment contained in cabinets or panels with service loops, each loop being at least 300 mm (12 inches) long. Equipment for fiber optics system shall be rack mounted, as applicable, in ventilated, self-supporting, code gauge steel enclosure. Cables shall be supported for minimum sag.

c. Cable Runs: Keep cable runs as short as possible. Allow extra length for connecting to the terminal board. Do not bend flexible coaxial cables in a radius less than ten times the cable outside diameter.

d. Use vinyl tape, sleeves, or grommets to protect cables from vibration at points where they pass around sharp corners, through walls, panel cabinets, etc.

6. Conceal cables, except in mechanical rooms and areas where other conduits and piping are exposed.

7. Permanently label or code each point of all field terminal strips to show the instrument or item served. Color-coded cable with cable diagrams may be used to accomplish cable identification.
8. Grounding: ground electrical systems per manufacturer's written requirements for proper and safe operation.

D. Install Sensors and Controls:

1. Temperature Sensors:

- a. Install all sensors and instrumentation according to manufacturer's written instructions. Temperature sensor locations shall be readily accessible, permitting quick replacement and servicing of them without special skills and tools.
- b. Calibrate sensors to accuracy specified, if not factory calibrated.
- c. Use of sensors shall be limited to its duty, e.g., duct sensor shall not be used in lieu of room sensor.
- d. Install room sensors permanently supported on wall frame. They shall be mounted at 1.5 meter (5.0 feet) above the finished floor.
- e. Mount sensors rigidly and adequately for the environment within which the sensor operates.
- f. Sensors used in mixing plenum, and hot and cold decks shall be of the averaging of type. Averaging sensors shall be installed in a serpentine manner horizontally across duct. Each bend shall be supported with a capillary clip.
- g. All pipe mounted temperature sensors shall be installed in wells.
- h. All wires attached to sensors shall be air sealed in their conduits or in the wall to stop air transmitted from other areas affecting sensor reading.
- i. Permanently mark terminal blocks for identification. Protect all circuits to avoid interruption of service due to short-circuiting or other conditions. Line-protect all wiring that comes from external sources to the site from lightning and static electricity.

2. Pressure Sensors:

- a. Install duct static pressure sensor tips facing directly downstream of airflow.
- b. Install high-pressure side of the differential switch between the pump discharge and the check valve.
- c. Install snubbers and isolation valves on steam pressure sensing devices.

3. Actuators:

- a. Mount and link damper and valve actuators according to manufacturer's written instructions.
- b. Check operation of damper/actuator combination to confirm that actuator modulates damper smoothly throughout stroke to both open and closed position.
- c. Check operation of valve/actuator combination to confirm that actuator modulates valve smoothly in both open and closed position.

4. Flow Switches:

- a. Install flow switch according to manufacturer's written instructions.
- b. Mount flow switch a minimum of 5 pipe diameters up stream and 5 pipe diameters downstream or 600 mm (2 feet) whichever is greater, from fittings and other obstructions.
- c. Assure correct flow direction and alignment.

d. Mount in horizontal piping-flow switch on top of the pipe.

E. Installation of Network:

1. Ethernet:

a. The network shall employ Ethernet LAN architecture, as defined by IEEE 802.3. The Network Interface shall be fully Internet Protocol (IP) compliant allowing connection to currently installed IEEE 802.3, Compliant Ethernet Networks.

b. The network shall directly support connectivity to a variety of cabling types. As a minimum provide the following connectivity: 10 Base 2 (ThinNet RG-58 A/U Coaxial cabling with BNC connectors), 10 Base T (Twisted-Pair RJ-45 terminated UTP cabling).

2. Third Party Interfaces: Contractor shall integrate real-time data from building systems by other trades and databases originating from other manufacturers as specified and required to make the system work as one system.

F. Installation of Digital Controllers and Programming:

1. Provide a separate digital control panel for each major piece of equipment, such as air handling unit, chiller, pumping unit etc. Points used for control loop reset such as outdoor air, outdoor humidity, or space temperature could be located on any of the remote control units.

2. Provide sufficient internal memory for the specified control sequences and trend logging. There shall be a minimum of 25 percent of available memory free for future use.

3. System point names shall be modular in design, permitting easy operator interface without the use of a written point index.

4. Provide software programming for the applications intended for the systems specified, and adhere to the strategy algorithms provided.

5. Provide graphics for each piece of equipment and floor plan in the building. This includes each chiller, cooling tower, air handling unit, fan, terminal unit, boiler, pumping unit etc. These graphics shall show all points dynamically as specified in the point list.

4.2 SYSTEM VALIDATION AND DEMONSTRATION

A. As part of final system acceptance, a System Demonstration is required (see below). Prior to start of this Demonstration, the contractor is to perform a complete Validation of all aspects of the Controls and Instrumentation System.

B. Validation

1. Prepare and submit for approval a Validation Test Plan including Test Procedures for the performance verification tests. Test Plan shall address all specified functions of the Engineering Control Center and all specified sequences of operation. Explain in detail actions and expected results used to demonstrate compliance with the requirements of this specification. Explain the method for simulating the necessary conditions of operation used to demonstrate performance of the system. Test Plan shall include a Test Check List to be used by the Installer's agent to check and initial that each test has been successfully completed. Deliver Test Plan documentation for the performance verification tests to the owner's representative 30 days prior to start of performance verification tests. Provide draft copy of operation and maintenance manual with performance verification test.

2. After approval of the Validation Test Plan, Installer shall carry out all tests and procedures therein. Installer shall completely

check out, calibrate, and test all connected hardware and software to insure that system performs in accordance with approved specifications and sequences of operation submitted. Installer shall complete and submit Test Check List.

C. DEMONSTRATION

1. System operation and calibration to be demonstrated by the Installer in the presence of the Architect or Owner's representative on random samples of equipment as dictated by the Owner's representative. Should random sampling indicate improper commissioning, the owner reserves the right to subsequently witness complete calibration of the system at no addition cost to the owner.
2. Demonstrate to authorities that all required safeties and life safety functions are fully functional and complete.
3. Make accessible , personnel to provide necessary adjustments and corrections to systems as directed by balancing agency.
4. The following witnessed demonstrations of field control equipment shall be included:
 - a. Pressure test control air piping at 1.25 times the design pressure. Pressure shall be applied in several stages, allowing time for the system to reach equilibrium. The test pressure shall not exceed the pneumatic test pressure for any pump, valve, or other component in the system under test. Pressure shall not drop more than 5% within 4 hours.
 - b. Observe HVAC systems in shut down condition. Check dampers and valves for normal position.
 - c. Test application software for its ability to communicate with digital controllers, operator workstation, and uploading and downloading of control programs.
 - d. Demonstrate the software ability to edit the control program offline.
 - e. Demonstrate reporting of alarm conditions for each alarm and ensure that these alarms are received at the assigned location, including operator workstations.
 - f. Demonstrate ability of software program to function for the intended applications-trend reports, change in status etc.
 - g. Demonstrate via graphed trends to show the sequence of operation is executed in correct manner, and that the HVAC systems operate properly through the complete sequence of operation, e.g., seasonal change, occupied/unoccupied mode, and warm-up condition.
 - h. Demonstrate hardware interlocks and safeties functions, and that the control systems perform the correct sequence of operation after power loss and resumption of power loss.
 - i. Prepare and deliver to the VA graphed trends of all control loops to demonstrate that each control loop is stable and the set points are maintained.
 - j. Demonstrate that each control loop responds to set point adjustment and stabilizes within one (1) minute. Control loop trend data shall be instantaneous and the time between data points shall not be greater than one (1) minute.
5. Witnessed validation demonstration of Operator's Terminal functions shall consist of:
 - a. Running each specified report.
 - b. Display and demonstrate each data entry to show site specific customizing capability. Demonstrate parameter changes.
 - c. Step through penetration tree, display all graphics, demonstrate dynamic update, and direct access to graphics.
 - d. Execute digital and analog commands in graphic mode.

- e. Demonstrate DDC loop precision and stability via trend logs of inputs and outputs (6 loops minimum).
 - f. Demonstrate EMS performance via trend logs and command trace.
 - g. Demonstrate scan, update, and alarm responsiveness.
 - h. Demonstrate spreadsheet/curve plot software, and its integration with database.
 - j. Demonstrate digital system configuration with interactive upline and downline load, and demonstrate specified diagnostics.
 - k. Demonstrate multitasking by showing dynamic curve plot, and graphic construction operating simultaneously via split screen.
 - l. Demonstrate class programming with point options of beep duration, beep rate, alarm archiving, and color banding.
- END -----